



A stochastic optimization model for frequency control and energy management in a microgrid

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Life Is On



Agenda

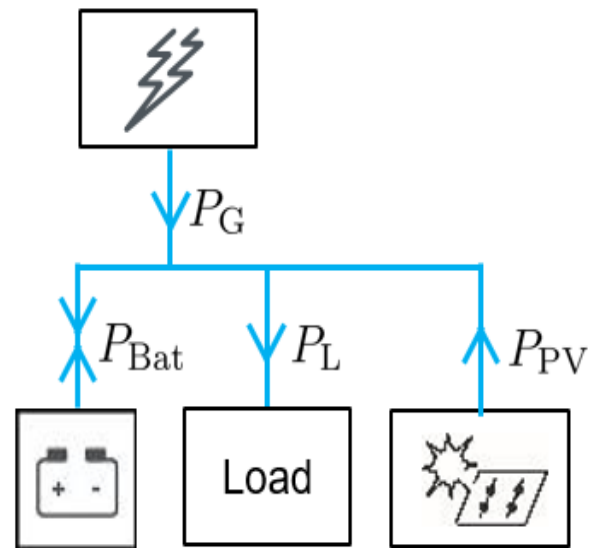
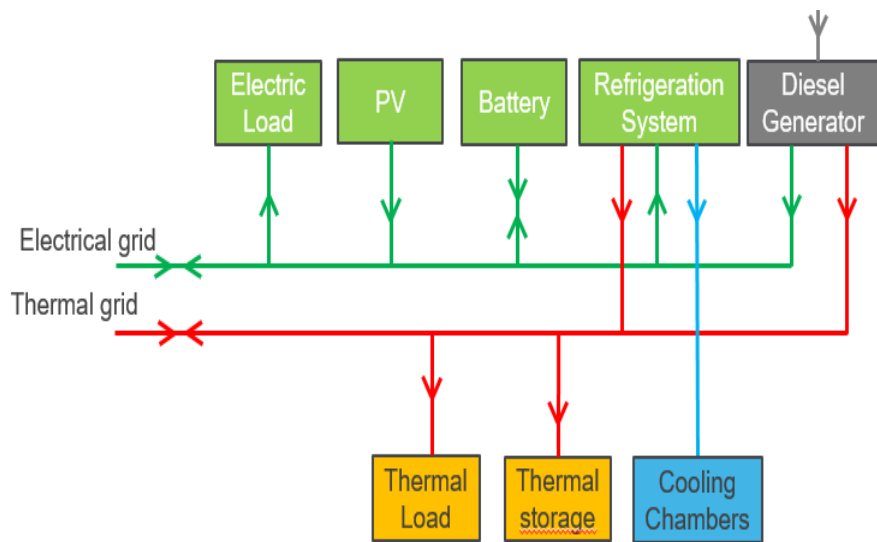
- 1 **Context of the work**
- 2 **Problem formulation**
- 3 **Out-of-sample simulations**
- 4 **Closed-loop simulations**
- 5 **Conclusions & future work**

The microgrid system description:



- ❖ Participating to the Frequency Containment Reserve market

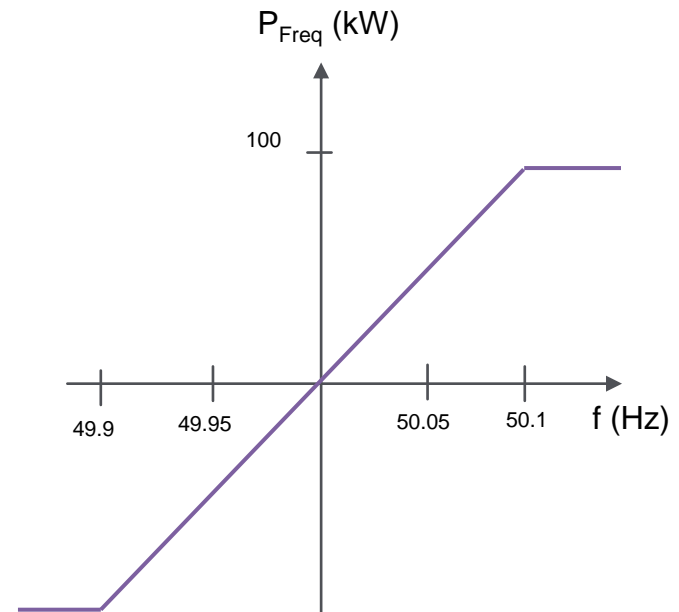
A thermal-electrical microgrid in Finland





Frequency Containment Reserve: requirements

- ❖ When $P_{\text{produced}} \neq P_{\text{consumed}}$: Frequency of the grid deviated from its nominal value (**50 Hz**)
- ❖ Need for frequency regulation to compensate deviations
- ❖ Any producer/consumer of a sufficient size (**> 100kW**) can participate in the FCR market



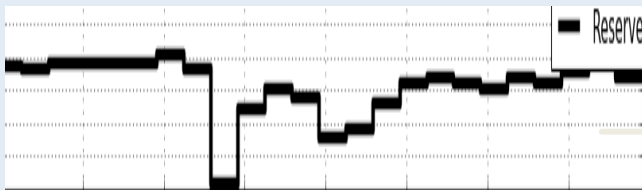


Frequency Containment Reserve: problems

•What is the optimal **day-ahead** frequency **reserve profile** to be submitted ?

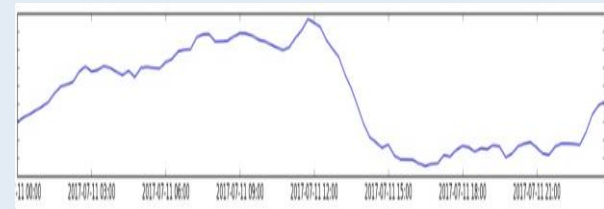
What is the the optimal **control strategy for the battery** to minimize energy costs?

Solve the **planning** optimization problem



Day J-1

Solve the **control** optimization problem



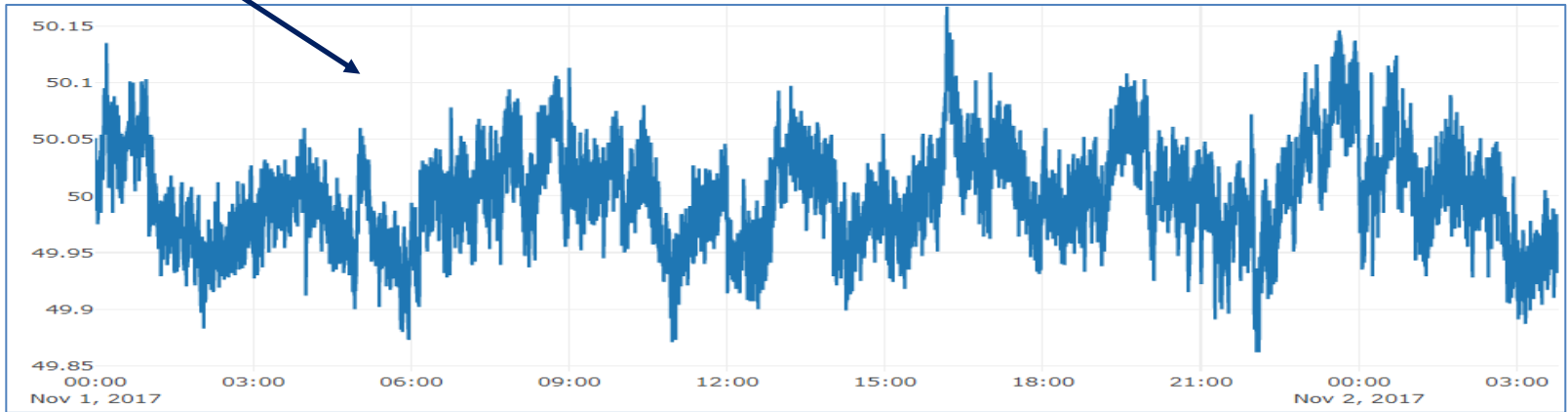
Day J

15'

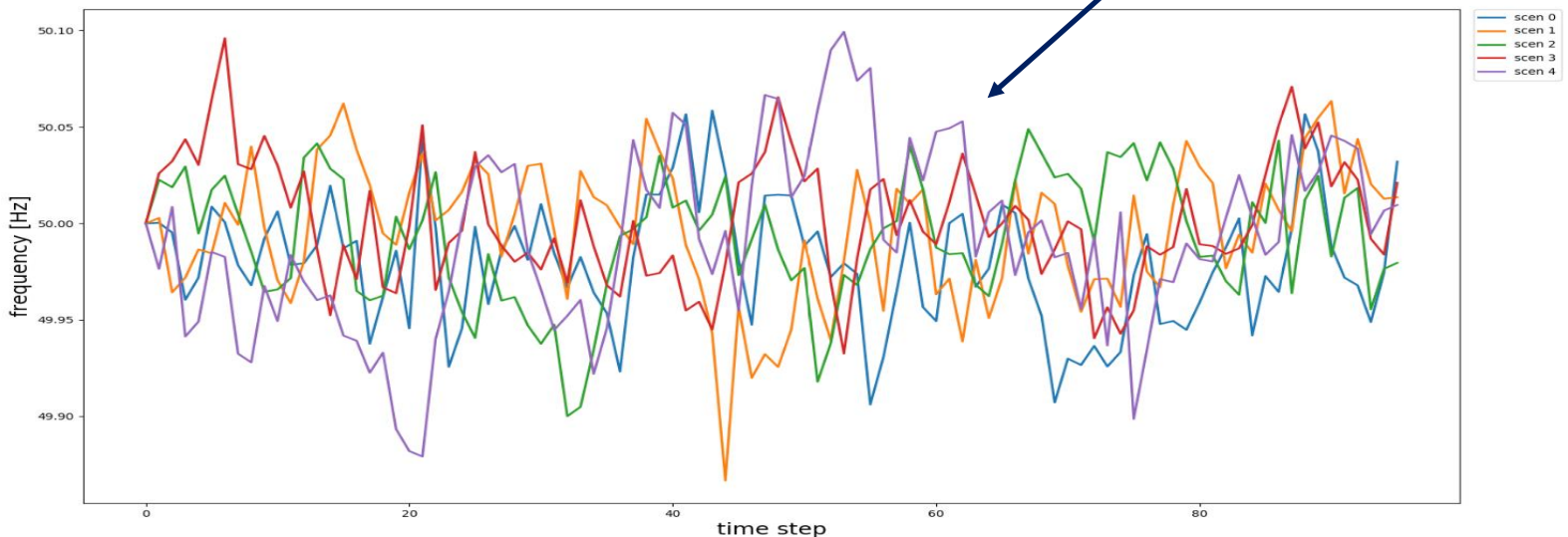


Frequency Containment Reserve: randomness of frequency deviations

Example of historical frequency deviation realization



Example of 5 generated scenarios using an AR process

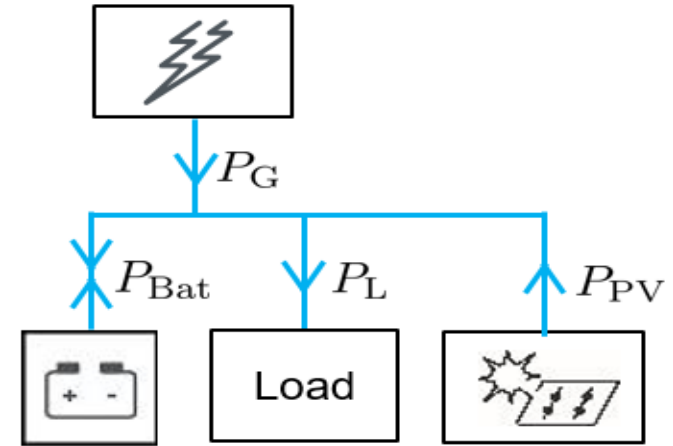


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Planning problem: deterministic



Revenue from supplied Energy TOU costs
FCR

$$\min -C_R \sum_{t=0}^{H-1} R_t + \sum_{t=0}^{H-1} C_{\text{TOU},t} P_{G,t}$$

$$\text{s.t. } P_{G,t} = P_{L,t} + P_{B,t} + P_{pv,t} \quad \forall t \quad \leftarrow \text{Balance equation}$$

$$SoC_{t+1} = SoC_t + P_{B,t} \cdot \Delta t \cdot \eta \quad \forall t \quad \leftarrow \text{Battery State of Charge}$$

$$P_{\min} + R_t \leq P_{B,t} \leq P_{\max} - R_t \quad \forall t \quad \leftarrow \text{Power and energy reserve for frequency regulation}$$

$$SoC_{\min} + 0.5R_t \leq SoC_t \leq SoC_{\max} - 0.5R_t \quad \forall t$$

$$R_t \geq 0 \quad \forall t.$$



Planning problem: stochastic

$$\begin{aligned}
 \min \quad & -C_R \sum_{t=0}^{H-1} R_t + \sum_{t=0}^{H-1} C_{\text{TOU},t} P_{G,t} \\
 \text{s.t.} \quad & P_{G,t} = P_{L,t} + P_{B,t} + P_{\text{pv},t} \quad \forall t \\
 & \text{SoC}_{t+1} = \text{SoC}_t + P_{B,t} \Delta t \cdot \eta \quad \forall t \\
 & P_{\min} + R_t \leq P_{B,t} \leq P_{\max} - R_t \quad \forall t \\
 & \text{SoC}_{\min} + 0.5R_t \leq \text{SoC}_t \leq \text{SoC}_{\max} - 0.5R_t \quad \forall t \\
 & R_t \geq 0 \quad \forall t.
 \end{aligned}$$

1

$$\begin{aligned}
 \min \quad & -C_R \sum_{t=0}^{H-1} R_t + \sum_{t=0}^{H-1} C_{\text{TOU},t} P_{G,t} \\
 \text{s.t.} \quad & P_{G,t} = P_{L,t} + P_{B,t} + P_{\text{pv},t} \quad \forall t \\
 & \text{SoC}_{t+1} = \text{SoC}_t + P_{B,t} \Delta t \cdot \eta \quad \forall t \\
 & P_{B,t} = P_{N,t} + R_t \Delta f_t \quad \forall t \\
 & P_{\min} + R_t \leq P_{N,t} \leq P_{\max} - R_t \quad \forall t \\
 & \text{SoC}_{\min} + 0.5R_t \leq \text{SoC}_t \leq \text{SoC}_{\max} - 0.5R_t \quad \forall t \\
 & R_t \geq 0 \quad \forall t.
 \end{aligned}$$

2

Random vector

Two-stage stochastic formulation:

$$\begin{aligned}
 \min \quad & -C_R \sum_{t=0}^{H-1} R_t + \sum_{t=0}^{H-1} C_{TOU,t} P_{G,t} \\
 \text{s.t.} \quad & P_{G,t} = P_{L,t} + P_{B,t} + P_{pv,t} \quad \forall t \\
 & Soc_{t+1} = Soc_t + P_{B,t} \cdot \Delta t \cdot \eta \quad \forall t \\
 & P_{B,t} = P_{N,t} + R_t \Delta f_t \quad \forall t \\
 & P_{\min} + R_t \leq P_{N,t} \leq P_{\max} - R_t \quad \forall t \\
 & SoC_{\min} + 0.5R_t \leq SoC_t \leq SoC_{\max} - 0.5R_t \quad \forall t \\
 & R_t \geq 0 \quad \forall t.
 \end{aligned}$$

2

$$\begin{aligned}
 \min \quad & -C_R \sum_{t=0}^{H-1} R_t + \mathbb{E} \left[\sum_{t=0}^{H-1} C_{TOU,t} P_{G,t} \right] \\
 \text{s.t.} \quad & P_{G,t} = P_{L,t} + P_{B,t} + P_{pv,t} \quad \forall t \\
 & Soc_{t+1} = Soc_t + P_{B,t} \cdot \Delta t \cdot \eta \quad \forall t \\
 & P_{B,t} = P_{N,t} + R_t \Delta f_t \quad \forall t \\
 & P_{\min} + R_t \leq P_{N,t} \leq P_{\max} - R_t \quad \forall t \\
 & SoC_{\min} + 0.5R_t \leq SoC_t \leq SoC_{\max} - 0.5R_t \quad \forall t \\
 & R_t \geq 0 \quad \forall t.
 \end{aligned}$$

3

Replace the term by its expected value



Sample Average Approximation:

$$\min -C_R \sum_{t=0}^{H-1} R_t + \mathbb{E} \left[\sum_{t=0}^{H-1} C_{TOU,t} P_{G,t} \right]$$

3

$$\text{s.t. } P_{G,t} = P_{L,t} + P_{B,t} + P_{pv,t} \quad \forall t$$

$$SoC_{t+1} = SoC_t + P_{B,t} \cdot \Delta t \cdot \eta \quad \forall t$$

$$P_{B,t} = P_{N,t} + R_t \quad \Delta f_t \quad \forall t$$

$$P_{\min} + R_t \leq P_{N,t} \leq P_{\max} - R_t \quad \forall t$$

$$SoC_{\min} + 0.5R_t \leq SoC_t \leq SoC_{\max} - 0.5R_t \quad \forall t$$

$$R_t \geq 0 \quad \forall t.$$

$$\min -C_R \sum_{t=0}^{H-1} R_t + \frac{1}{N} \left[\sum_{i=1}^N \sum_{t=0}^{H-1} C_{TOU,t} P_{G,t}^{(i)} \right]$$

4

$$\text{s.t. } P_{G,t}^{(i)} = P_{L,t} + P_{B,t}^{(i)} + P_{pv,t} \quad \forall i, \forall t$$

$$SoC_{t+1}^{(i)} = SoC_t^{(i)} + P_{B,t}^{(i)} \cdot \Delta t \cdot \eta \quad \forall i, \forall t$$

$$P_{B,t}^{(i)} = P_{N,t}^{(i)} + R_t \Delta f_t^{(i)} \quad \forall i, \forall t$$

$$P_{\min} + R_t \leq P_{N,t}^{(i)} \leq P_{\max} - R_t \quad \forall i, \forall t$$

$$SoC_{\min} + 0.5R_t \leq SoC_t^{(i)} \leq SoC_{\max} - 0.5R_t \quad \forall i, \forall t$$

$$R_t \geq 0 \quad \forall t.$$

Averaged value on N scenarios

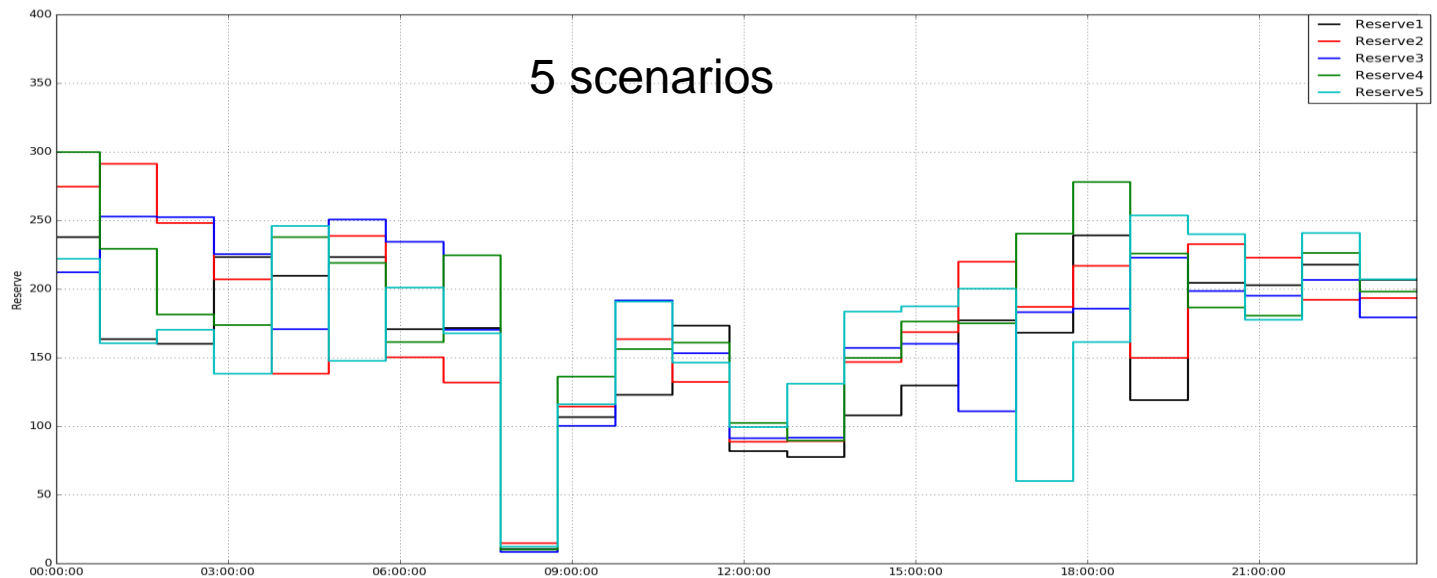
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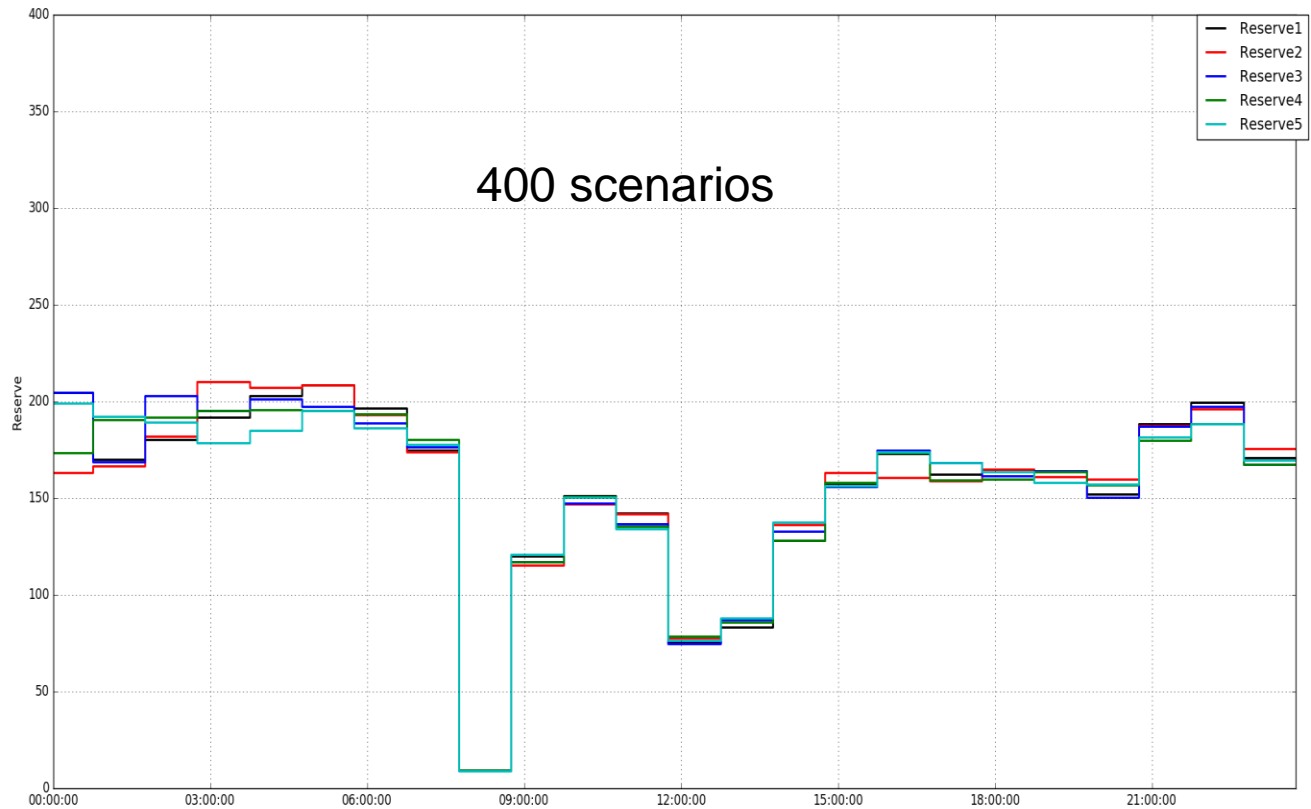


Impact of the number of scenarios:

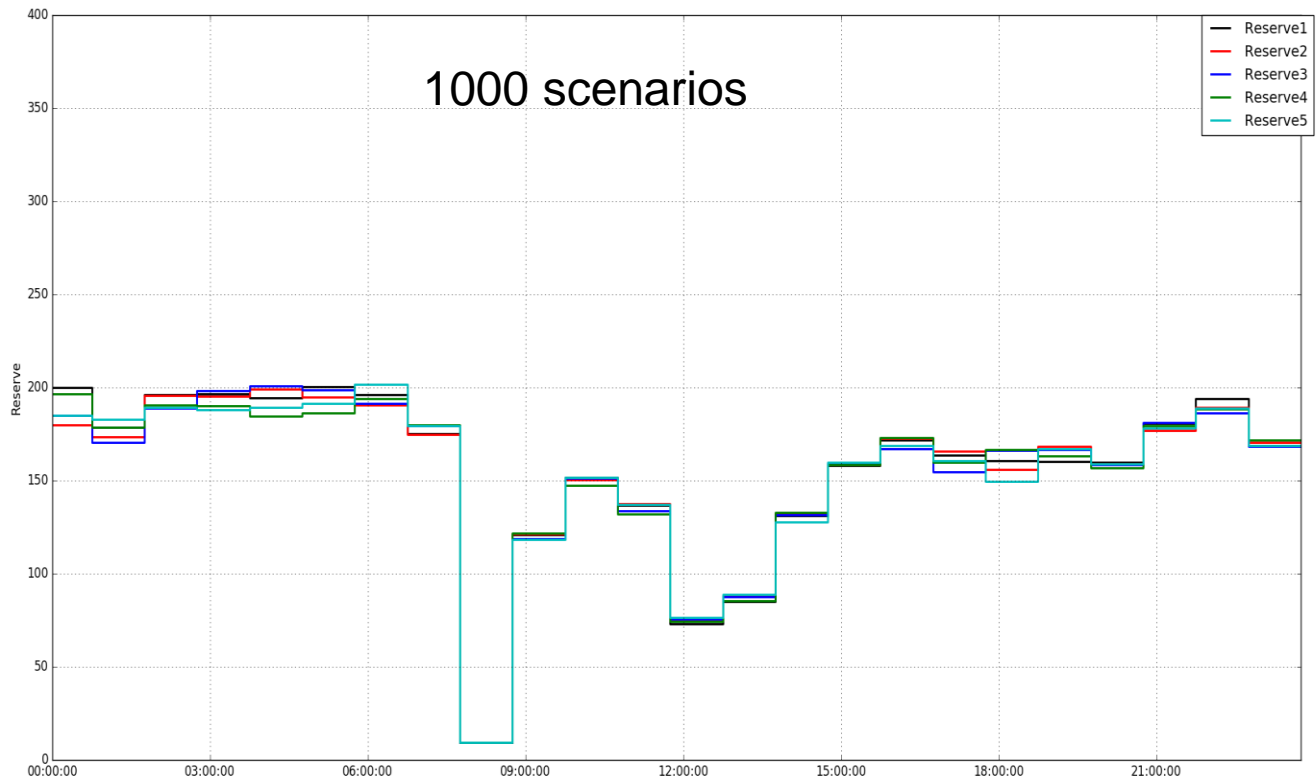
- **Solve the planning problem several times with different numbers of scenarios (N=5, 400, 1000)**



Impact of the number of scenarios:

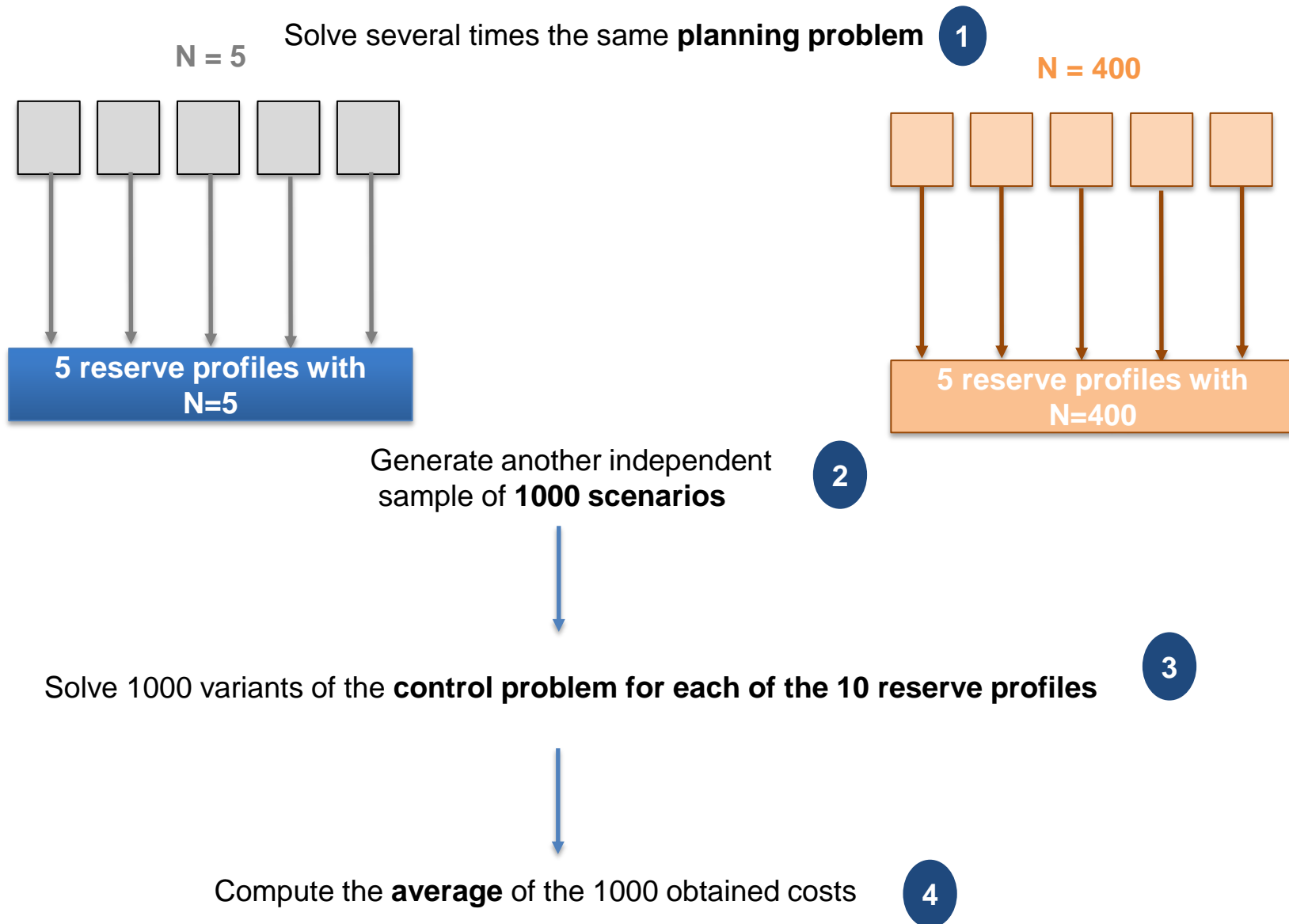


Impact of the number of scenarios:



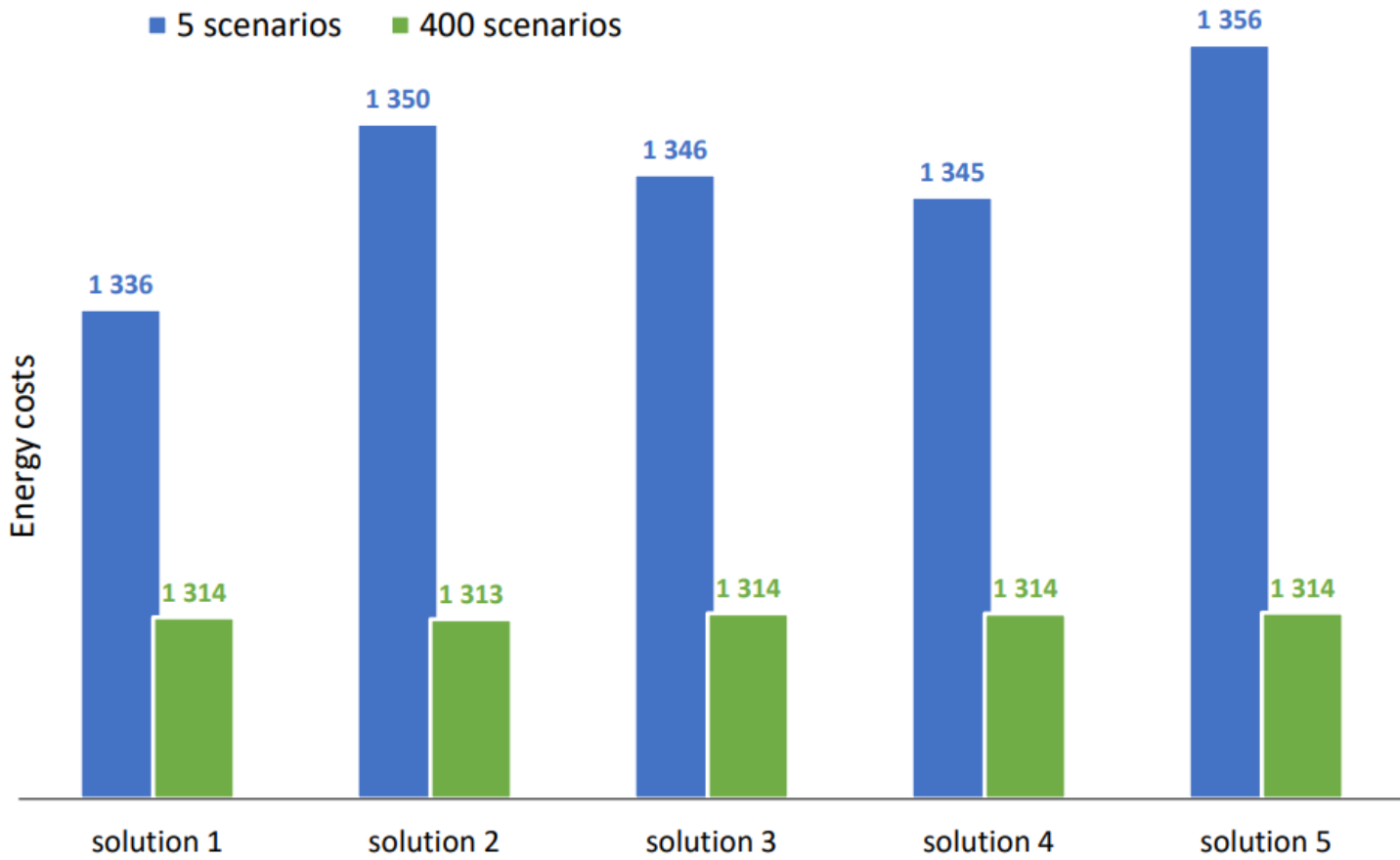


Out-of-sample simulations:





Out-of-sample simulations:

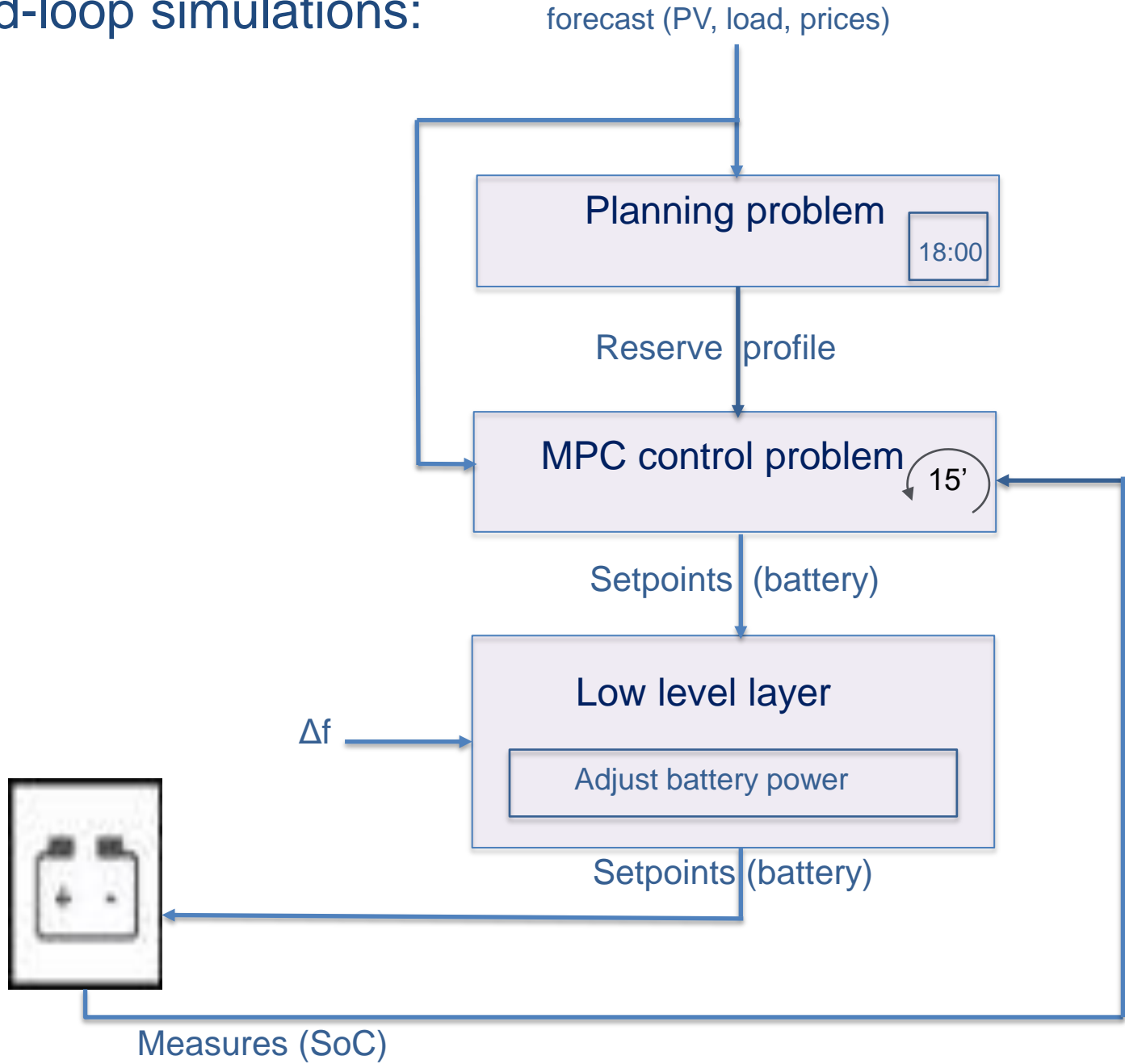


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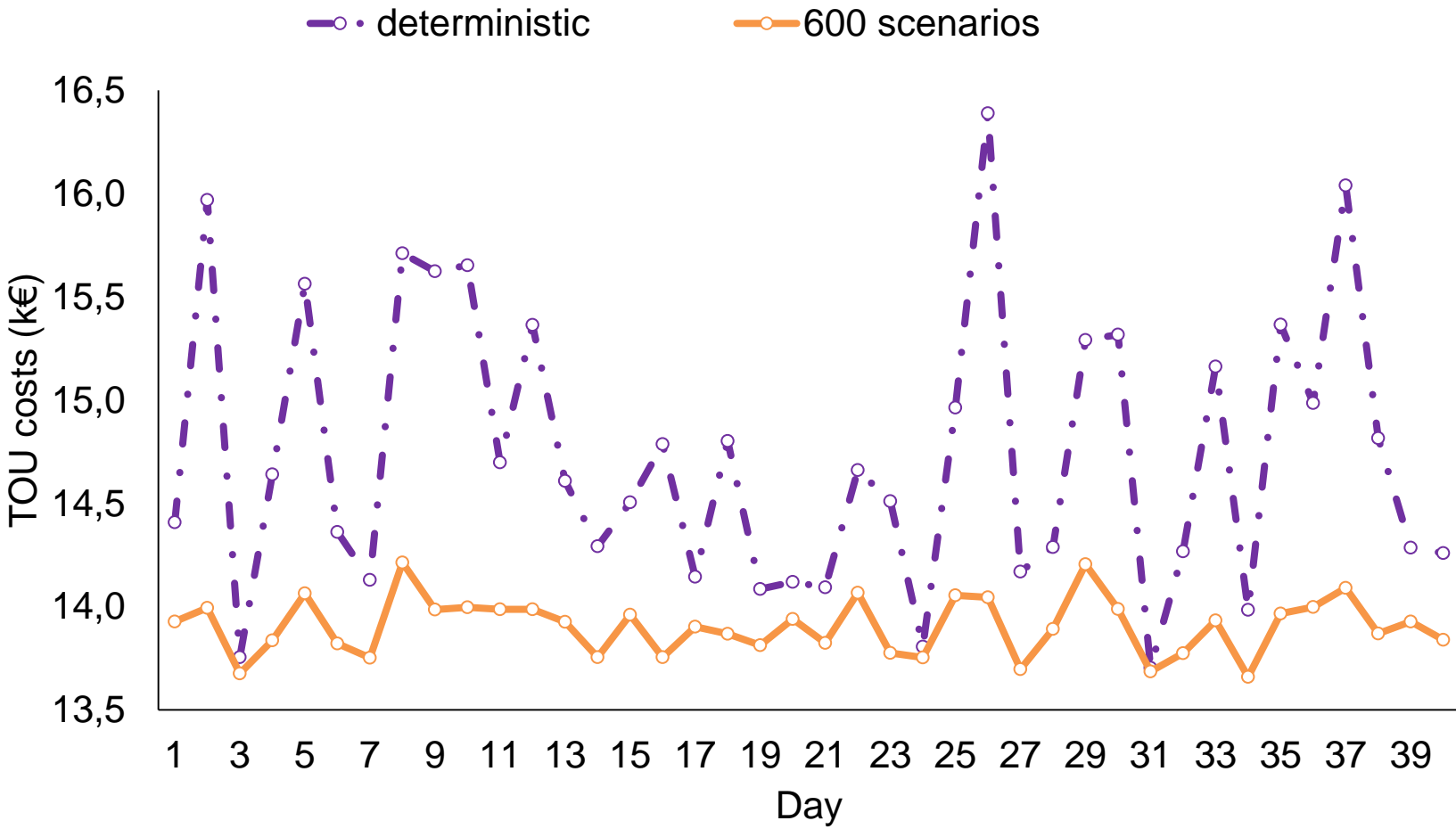
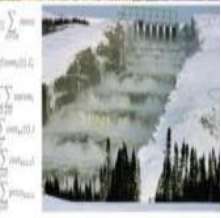


Closed-loop simulations:

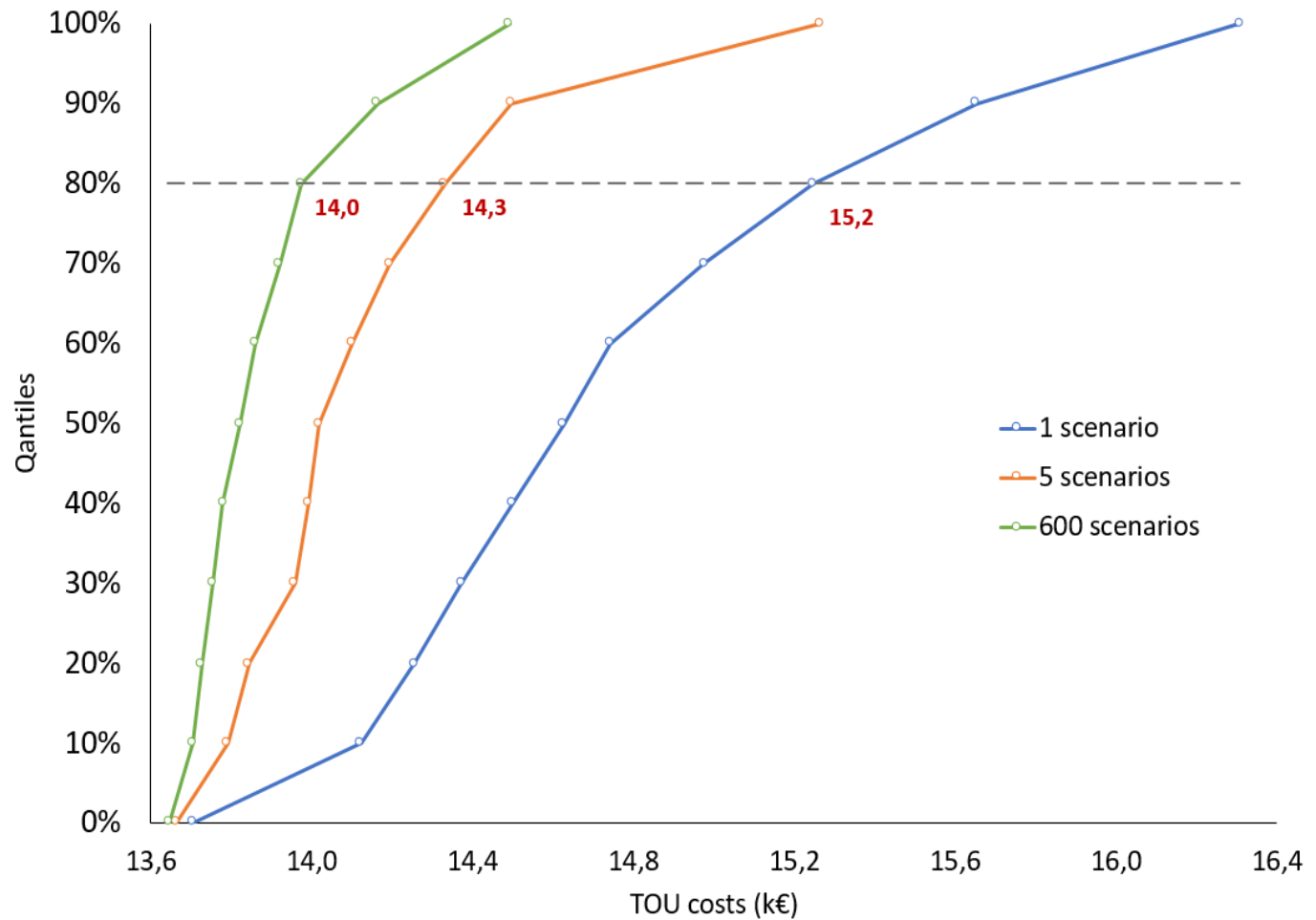




Closed-loop simulations: deterministic VS stochastic:



Closed-loop simulations: impact of the number of scenarios



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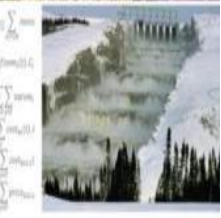
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Conclusion

- Development of a stochastic programming approach to deal with the uncertainty in FCR
- Comparison with a classical/ deterministic approach
- Stochastic programming: reduced energy costs, reduced risks and a better predictability

Future work

- **Reducing the computational time** (decomposition/ clustering/ scenario reduction techniques...)
- **Considering other sources of uncertainty** (load, PV production, electricity prices...)
- **Extending to multi-energy optimization** (thermal and electrical)



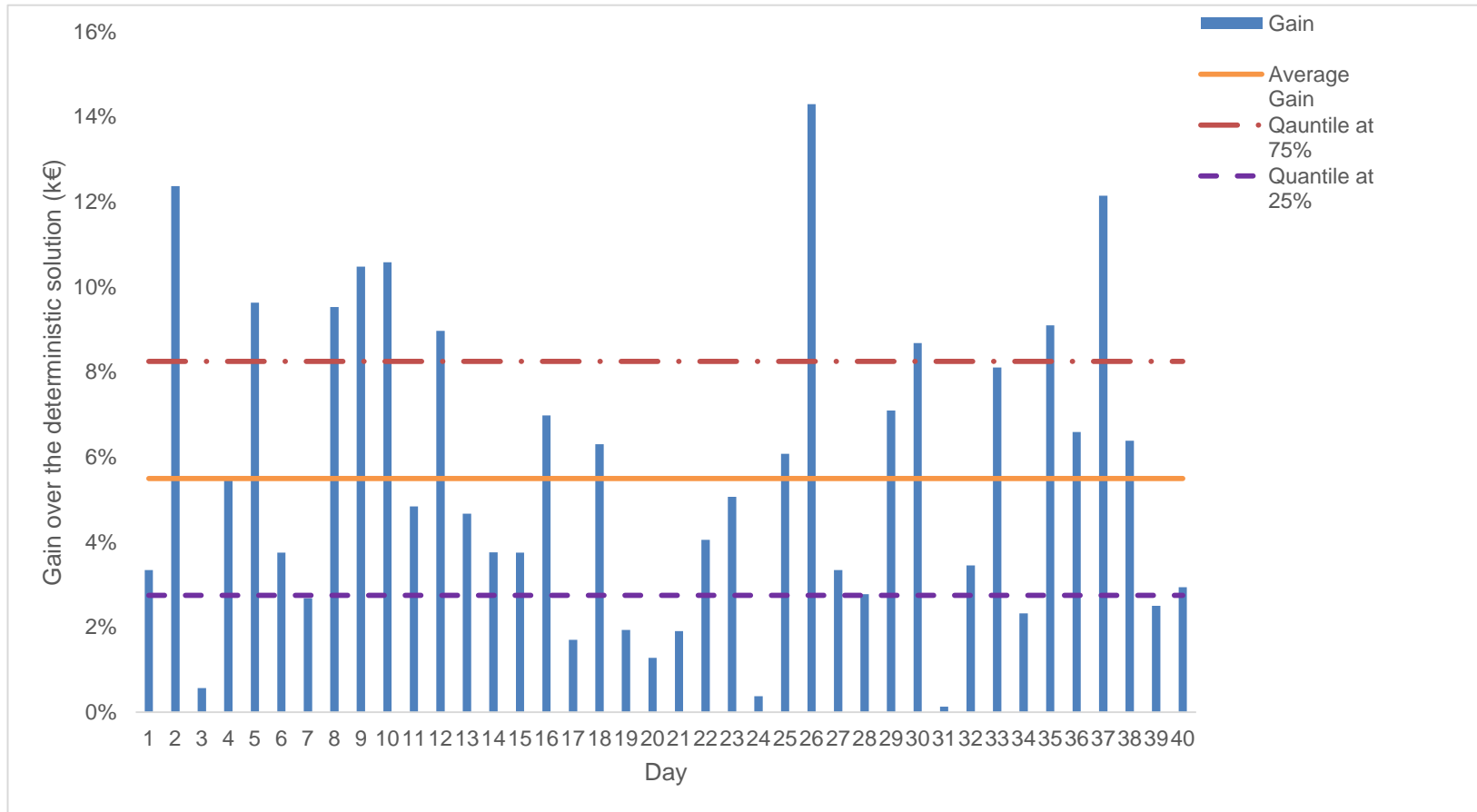
Thank you for your attention



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Closed-loop simulations: deterministic VS stochastic:

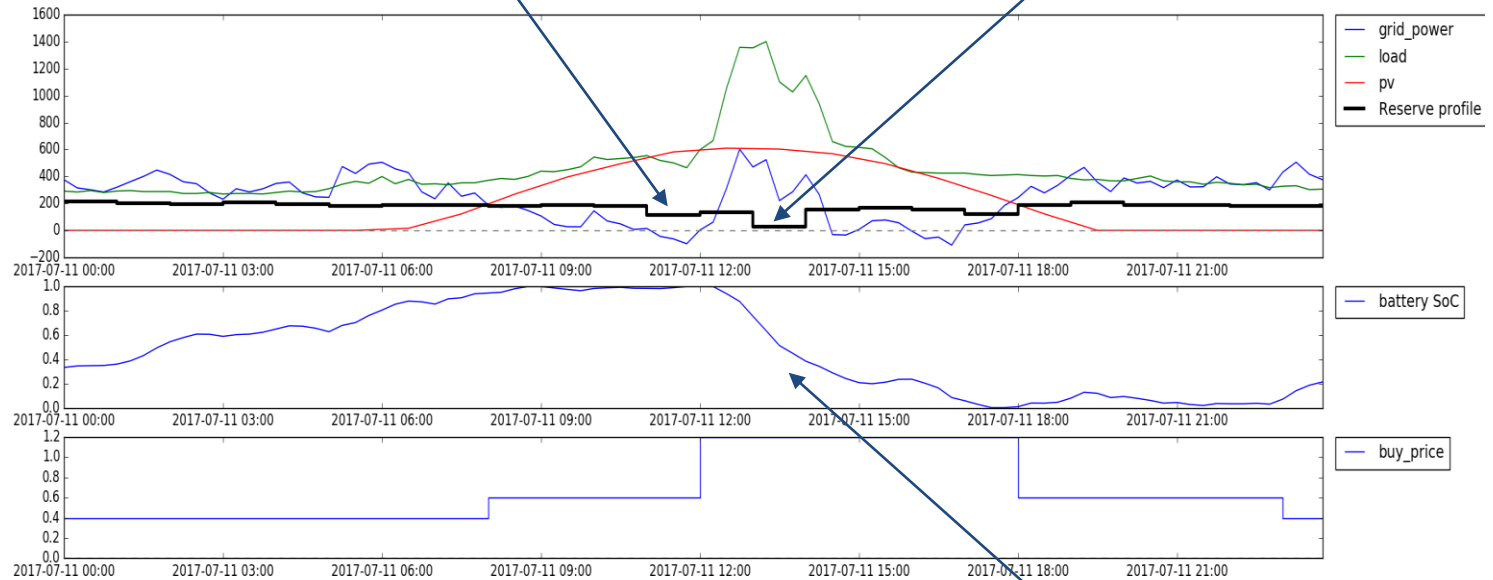




Closed-loop simulations: overview of the results

Provide less frequency reserve to store surplus PV

No FCR reserve: battery used only for self-consumption



Discharging the battery during high price periods