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An overview of molten polymer drawing instabilities

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Abstract

Drawing instabilities and rupture are a serious limitation in polymer fibre and film processing. Onset of these defects depends on the processing conditions, on heat transfer, and on the rheology of the polymer even if some may be encountered for Newtonian fluids. The main part of this paper is devoted to the different forms of the draw resonance instability encountered in fibre spinning, cast-film and film blowing. The time dependent equations are presented for the simplified situation of constant width cast-film. Results of the two possible modelling strategies, linear stability analysis and direct simulation, applied to the different fibre and film processes are discussed.

1. Introduction

Numerous polymer processes (fibre spinning, cast film or film blowing) involve a stretching step after the initial extrusion step. Drawing instability (draw resonance) is a typical defect encountered during stretching in air. The existence of an air-polymer interface allows the onset of a periodic instability leading to very large variations of thickness, width and diameter. This paper deals with the different forms of the drawing instabilities encountered in classical processes such as fibre spinning, cast-film and blown film.

In fibre spinning, a polymer (generally Polyester or Polyamide) is first melted by heat transfer and viscous dissipation in a screw/barrel device and then forced in a spinning pack consisting of a metal plaque with several (hundred) holes (typical diameter between 0.3 and 1 mm). The several hundred filaments emerging from the spinning pack are then stretched in order to obtain the final required diameter of textile filaments (several ten micrometers). This requires high draw ratios (ratio between the drawing wheel velocity and the die exit velocity), under severe cooling conditions (air jet or water bath) in order to obtain a solidified spun fibre at the drawing wheel. In addition, stretching the filament allows the development of appropriate mechanical properties. The stretching distance may vary from a few centimeters for water bath cooling systems to several meters for classical air jet cooling.

There are two families of processes for polymer film production:

- In the cast-film process, the polymer is melted in an extruder and forced in a coat hanger flat die to produce an initial web (1 or 2 m in width, 1 mm in thickness) which needs then to be stretched between the die and a chill roll in order to obtain the required film thickness (several ten microns is required for packaging applications).
- In the blown film process, the molten polymer is forced within a tube die. This tube is then simultaneously stretched in the vertical direction by nip rolls, inflated by an internal pressure and cooled by external air rings. A more precise description of these processes may be found in Agassant et al. (1996).

Let us note that both diameter of the holes of a spinning pack and final gap of a coat-hanger or tube die need to be sufficiently large in order to limit the required extrusion pressure. It leads naturally to an important stretching rate (Draw ratio Dr). In fibre and film production, two kinds of defects may be observed at high draw ratios, periodic fluctuations of the diameter (fiber spinning) or of both the film thickness and width (cast-film) or the film thickness and the bubble diameter (film blowing) but also filament or web rupture. All these phenomena depend on the stretching distance, the cooling conditions and the rheology of the molten polymer, but it is important to mention that some of these instabilities may be encountered even for Newtonian fluids (glass fibre processing for example). These instabilities are the more drastic limitation for process productivity, and at present it is a real challenge to master and then to postpone their occurrence.

Several extensive review papers have been devoted to the experimental and theoretical analyses of these instabilities : Co (2005) for cast film, Jung and Hyun (2005, 2006) for fibre spinning and film blowing.

In the present paper, various drawing instability experiments performed at CEMEF-Mines ParisTech or in cooperation with Ecole Polytechnique-Montreal are presented in the next paragraph. The time dependent stretching equations for the constant width cast film process are presented as a reference case in the third paragraph. The different strategies used to explain draw resonance instabilities as well as fibre or web breakage at high draw ratios are discussed in the last paragraphs.

2. Experiments

Most of the published experiments have been devoted to filament stretching instabilities. The basic experiment may be done with purely viscous (corn syrup for example, Chang and Denn, 1979) or viscoelastic (molten polymers) fluids (Kase, 1974; Ishihara and Kase, 1975; Demay, 1983). The experiments consist in extruding a fluid from a capillary die at a constant flow rate (velocity u_0) and increasing progressively the take-up velocity u_L imposed at a short distance from the die, which corresponds to a quasi-isothermal situation. The fiber diameter is continuously recorded along the stretching path and after solidification (for molten polymers). Stretching step intensity is evaluated by the so called Draw ratio (a dimensionless number) defined as $Dr = u_L / u_0$. At low Draw ratio, the stretching flow is stable which means that the filament diameter is constant in time and any perturbation decreases and goes to zero with time (figure 1a). When increasing the Draw ratio above a critical value Dr^* which is of the order of magnitude of one to several tens, the flow becomes unstable: This means that a sustained periodic diameter fluctuation develops (figure 1b). It appears just at the die exit and then propagates till the extremity of the stretching path (Hyun, 1999). When the Draw ratio is increased again, the amplitude of the periodic instabilities increases till very large values (a ratio of 10 between the maximum and the minimum diameter may be reached) (figure 1c). Ghiljels and Ente (1980) identified directly the occurrence of these instabilities by recording continuously the stretching force which is obviously very small (of the order of several milli-Newton). When increasing the stretching distance, the process becomes progressively non isothermal and the critical Draw ratio Dr^* increases too (Blyler and Gieniewski, 1980; Gupta and Drechsel, 1981; Demay, 1983). When the stretching distance L is sufficiently large, more complex phenomena occur as stress induced crystallization involving changes in the temperature field. This may result in a strong necking phenomenon in the crystallization zone which prevents from the drawing instability development (Shin *et al.*, 2006; Kohler and McHugh, 2008). When stretching polymers of increasing elasticity in quasi-isothermal conditions, the critical Draw ratio remains first more or less constant and then the periodic instability disappears and frequent filament breakages are then observed (Chang and Denn,

1979). Spinning experiments have been performed with Polyesters of various macromolecular architecture, which results in different viscoelastic properties (White and Yamane, 1985). As pointed out by Demay and Agassant (1985) different instabilities may be observed depending on the viscoelastic properties (figure 2). The Deborah number De weights the mean relaxation time of the polymer λ to a characteristic time of the process L/u_0 . For polyester A and C, whatever the value of the extrusion velocity u_0 , the spinning process becomes unstable for critical draw ratios Dr^* between 15 and 20. For Polyester B, the periodic instability is never encountered, but filament breakage. The behaviour of polyester D is in-between the preceding ones: periodic instabilities at low extrusion velocity (low Deborah number) and filament breakage at high extrusion velocity (high Deborah number).

In the cast-film process, both thickness and width periodic fluctuations are observed above a critical Draw ratio of the same order of magnitude as in fibre spinning. But the phenomenon is more complex because film stretching induces also width reduction (called neck-in) and related lateral over-thicknesses (called dog-bone defect). This is the reason why very few experimental results are available. Barq *et al.* (1990) performed careful and tedious width and thickness fluctuation measurements (in the central part of a PET film and along the edges) on very long distances (figure 3). They point out periodic fluctuations with the same period for width and thickness. The maximum thickness in the central part of the film corresponds more or less to the minimum width, but the two periodic fluctuations do not balance with another which means that the flow rate at take-up is also a function of time. Shin *et al.* (2007a) recorded the film thickness in the central part of HDPE and LDPE films as a function of time. Agassant *et al.* (2006) were able to identify the occurrence of the cast film instability by recording continuously the stretching force as a function of time for various LLDPE films (figure 4). This is easier than in fibre spinning because the stretching force is much more important (several Newtons). Bourrigaud *et al.* (2006) showed for a series of LDPE of various viscoelastic properties that web rupture may be observed at a Draw ratio which decreases when the Deborah number increases (figure 5).

In film blowing, stretching intensity is evaluated by the Draw ratio but also by the Blow-up ratio ($Bur = R_L / R_0$, R_L is the final bubble radius and R_0 the tube die radius). The same type of phenomenon as in cast-film may be expected, that means a periodic fluctuation of thickness and diameter (figure 6) (Kanai and White, 1984; Minoshima and White, 1986; Ghaned-Fard *et al.*, 1996; Laffargue *et al.*, 2002, 2010). In fact a non-axisymmetric instability may also be observed, which corresponds to a helical shape of the bubble between the die exit and the film freezing line (figure 7). Ghaned-Fard *et al.* (1996) developed a sophisticated optical device to capture quantitatively simultaneously the diameter of the bubble and the location of its centre at each position between the die exit and the freezing line. Figure 8 shows, for a Blow-up ratio (Bur) of 2.75, that the bubble radius remains constant for a Draw ratio (Dr) of 9.4. When increasing Dr to 9.9, pronounced periodic radius variations are observed. When decreasing again Dr to 9.4, the bubble radius stabilizes. At the same time, the centre of the bubble remains stable. On the contrary, for a Bur of 3.25, the bubble radius remains constant when increasing Dr from 6.6 to 7.1, but at the same time the centre of the bubble rotates (figure 9) in an horizontal plane giving a helical shape to the bubble. Laffargue *et al.* (2010) performed film blowing experiments on various extrusion lines but with the same LLDPE. They point out the existence of a stability hill splitting stable and unstable blowing conditions (for both axisymmetric and helical instabilities (figure 10)).

2. Modelling strategy : constant width cast-film process

The physics which governs the appearance of the drawing instability may be explained qualitatively. Having in mind that the requirement of the process is to accelerate the molten polymer from the die exit (velocity u_0) to the take up wheel (velocity u_L), one may consider that this may be done in two different ways:

- at low Draw ratio the velocity increases progressively from $x=0$ to $x=L$, the flow is steady and the dissipated energy is mainly due to stretching,
- at higher Draw ratio, a time dependant flow will require less energy than the steady one: first flow packets are formed at die exit and then these packets are accelerated from u_0 to u_L at low deformation rate and then at low energy expense because inertia is negligible.

Models will be built to account for the onset and the development of the draw resonance instability but “without necessarily revealing the fundamental cause of the instability itself” (Hyun, 1999). The first step consists in obtaining a time dependant model for the stretching flow. A web with an initial thickness $e_0 \approx 1mm$ is stretched between a die and a chill-roll (or a water bath) on a distance $L \approx 10cm$. The width W of the web is supposed to be constant (the neck-in phenomenon is neglected) and the velocity u and the current thickness e are assumed to be uniform in each cross-section (figure 11). As the aspect ratio ($\varepsilon = e_0 / L$) of the stretching flow is small, it is possible to build a simple but realistic membrane model (Yeow, 1976; Antukar and Co, 1988 ; Barq *et al.*, 1990, 1994). Let us note x the distance to the extrusion die ($0 < x < L$) and t the time.

- Mass conservation writes:

$$\frac{\partial}{\partial t}(e) + \frac{\partial}{\partial x}(eu) = 0 \quad (1)$$

- Assuming a Newtonian behaviour (viscosity η) and neglecting the shear terms in front of the elongation terms leads to the Trouton equation for film stretching:

$$\sigma_{xx} = 4\eta \frac{du}{dx} \quad (2)$$

- The force balance writes, neglecting mass forces and inertia:

$$F = eW\sigma_{xx} = \text{constant} \quad (3)$$

- Boundary conditions imposed by the process are the following:

$$u(t; 0) = u_0 ; u(t; L) = u_L ; e(t; 0) = e_0 \quad (4)$$

Let us recall that u_0 and u_L are respectively velocity at die exit and take up. It is to notice that the final thickness is imposed only if the process is steady. It is then possible (and in this case very easy) to compute a steady (not time dependant) flow. It writes:

$$\bar{u}(x) = u_0(Dr)^{\frac{x}{L}} \quad \bar{e}(x) = e_0(Dr)^{-\frac{x}{L}} \quad (5)$$

The key point is to know if this steady flow is stable (really observed in the experiments). It means that a small perturbation of the steady state solution (5) introduced in equations [1-4] decreases with time up to vanish. Two different strategies (giving in fact complementary information) may be used.

- The first one is direct numerical simulation. Equations [1-4] are numerically solved according to variables t and x using a suited time and space scheme. The initial data at $t = 0$ is the stationary solution slightly disturbed. If this initial perturbation decreases and goes to zero, the process is stable. If the initial perturbation develops, the process is unstable. This method is relatively costly because of the time and space discretization

but is efficient to determine the periodic flow far away from transition (at relatively high Draw ratio). Some examples will be presented in the next paragraph.

- The other one is linear stability analysis which allows determining rapidly the critical parameters (critical draw ratio) for onset of the instability. In this case a perturbed solution of the following form is introduced.

$$u(x) = \bar{u}(x) + \exp(\lambda t)\hat{u}(x) \quad e(x) = \bar{e}(x) + \exp(\lambda t)\hat{e}(x) \quad (6)$$

In this equation, λ is an eigenvalue (a complex number) and $\hat{u}(x)$ and $\hat{e}(x)$ are eigenfunctions. Linearized equations are obtained by substituting the perturbed values of velocity and thickness (equation 6) in equations [1-4] and neglecting terms of order 2 according to $\hat{u}(x)$ and $\hat{e}(x)$. This system allows computing the dominant eigenvalues λ (there are theoretically an infinite number of eigenvalues) and associated eigenfunctions. The steady flow is stable if all the eigenvalues have a negative real part. The steady flow becomes unstable if the real part of a pair of complex conjugate dominant eigenvalues vanishes for $Dr=Dr^*$ ($\lambda = \pm i\omega$) and becomes positive for $Dr > Dr^*$. This is the general framework of the Hopf bifurcation theory. For $Dr > Dr^*$ the steady flow becomes unstable and generally a stable periodic flow appears. At transition between stable and unstable flow, the period is determined by the corresponding imaginary part of the eigenvalue ($T = 2\pi / \omega$). This simple model predicts the onset of the instability for a critical Draw ratio $Dr^*=20.2$ and it will be seen in the following that mechanical and thermal processing conditions as well as polymer rheology can influence largely the value of the critical Draw ratio. However this order of magnitude is in good agreement with experimental measurements.

These mathematical approaches described in a simple case have to be extended to account for more realistic situations:

- Geometry and kinematics: neck-in and varying thickness for the cast film process, axisymmetric situation in fibre spinning, non-uniform velocity profile through the thickness when the stretching distance decreases (the aspect ratio ε is no more small), non-axisymmetric bubble shape to account for the helical defect in film blowing.
- Heat transfer: as soon as the stretching distance is significant, the polymer temperature decreases and the energy equation as well as the temperature dependence of the viscosity have to be accounted for.
- Constitutive equations: The Newtonian behaviour is a crude approximation for polymer stretching. Viscoelastic constitutive equations need to be accounted for and, surprisingly, even an upper-convected Maxwell constitutive equation provides qualitative results.

Jung and Hyun (2005) proposed a more physical understanding of the development of these drawing instabilities based on different kinematic waves travelling along the stretching line.

In the following sections, the stability of the different stretching processes will be studied, taking progressively into account heat transfer, enriched kinematics and constitutive equations.

4. Cast-film process

4.1. Influence of cooling

In the cast-film process, the stretching distance is generally as small as possible in order to limit neck-in and the related dog bone defect (Silagy, 1996) and so temperature remains more or less uniform. For some coating application, this stretching distance is more important (for geometrical constraints) and temperature decreases, but crystallization temperature is generally not reached before the contact point with the chill roll. The temperature balance equation writes:

$$\rho c e \left(\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} \right) = -h_c (T - T_\infty) \quad (7)$$

In this equation ρ denotes the polymer density (function of the temperature), c the heat capacity, T the mean temperature in the thickness, (which is consistent with the shell approximation for the kinematics), T_∞ the surrounding temperature (a complex compromise between air and tool temperature) and h_c the heat transfer convection coefficient (free or forced convection depending on the web velocity). System of equations [1-4, 7] is completed to account for the influence of temperature on viscosity. Using the same perturbation procedure as in the preceding paragraph, the stability of the process is determined as a function of the Stanton number St which represents a non-dimensional value of the heat transfer coefficient. It is found that cooling stabilizes largely the process up to conditions stable for any values of the draw ratio at large enough values of the Stanton number.

4.2. Influence of the neck-in phenomenon

In order to account for the width reduction the thin shell membrane model is enriched in two successive steps:

- First, both thickness and velocity in the stretching direction $u(x)$ are supposed to remain constant through the width of the web $W(x)$. The velocity component $v(x,y)$ in the transverse direction has to be introduced but the continuity equation allows to express it as a function of x : $v(x,y) = yf(x)$. The linear stability analysis allows computing the value of the critical Draw ratio Dr^* as a function of the shape factor of the film $A=L/W$ (Silagy et al., 1996, 1998). The case $A=0$, corresponds to a very short stretching distance and in this situation the constant width cast-film analysis developed in the preceding paragraph is valid (the critical draw-ratio is $Dr^*=20.2$). Increasing A value means increasing the drawing distance and the critical Draw ratio Dr^* increases too. For example, for $A=1$, the value of the critical Draw ratio is increased by 50% as compared to $A=0$ (figure 12).
- The membrane model is then enriched to capture both development of the dog bone defect and neck-in by considering thickness and mean velocities in stretching and transverse directions to be functions of x and y ($e(x,y)$, $u(x,y)$ and $v(x,y)$). Direct numerical simulation was used by Silagy *et al.*, (1998). Figure 13 shows the thickness as a function of time for increasing values of the Draw ratio after introducing at $t=0$ a small arbitrary perturbation of the steady flow ($A= 0.5$). For $Dr < 21$, the initial perturbation vanishes rapidly. For $Dr=27$, a small, but non periodic, perturbation is observed. For $Dr=31.5$ a periodic well marked perturbation develops and grows slowly in amplitude. It becomes very important for $Dr=36$ and saturation of the amplitude is rapidly reached (with a ratio of eight between the maximum and the minimum thickness). As compared to the linear stability analysis, the border between stable and unstable drawing regime is less precisely defined but it allows predicting the shape of the film in unstable conditions: figure 14 shows that width and thickness fluctuations (in the central part and at the periphery of the film) as a function of time are in phase opposition which is in agreement with experiments

of figure 3. Figure 12 compares the 2D direct numerical stability simulation and the 1D linear stability analysis. The development of the dog bone defect in the 2D model could contribute to increase the stability of the process: for $A=1$, the critical Draw ratio is around 40 for the 2D model as it was around 30 for the 1D model.

4.3 : Validity of the membrane model : 2D transverse simulation

The membrane model previously described assumes a constant velocity profile through the thickness. This hypothesis is clearly valid in the stretching part of the flow i.e at a distance x larger than one or several thickness of the die gap. To describe precisely rearrangement from a shear flow in the slit die (the extremity of the coat hanger die) to a stretching flow, it is necessary to use a 2D model in the (x, z) plane (coordinates of figure 11). For sake of simplicity it is assumed as previously that the fluid has a Newtonian behaviour and that mass forces, inertia and surface tension are neglected. A 2D Stokes problem has to be solved on an unknown domain and determination of the polymer-air interface is a part of the solution. It is a so called free interface problem and two strategies are then possible:

- If a surface tracking method is used the kinematic and dynamic interface boundary conditions are explicitly enforced. The Stokes problem is solved on a computation domain which is restricted to the polymer flow. Interface with air is determined by successive iterations (by adjusting the position of the nodes on the interface) to satisfy the kinematic interface equation. This first strategy is relatively precise but unable to describe transient evolution of the interface. The linear stability method is then used to predict onset of draw resonance (Souli *et al.*, 1993).
- If a surface capturing method is used the computation domain is extended to the neighbourhoods of the air interface and the Stokes problem is coupled with a transport equation. Classical approaches are the level set and the Volume of Fluid method. A complex mesh refinement is required in the vicinity of the interface but it allows capturing severe topological changes of the flow domain. Then a time and space numerical scheme (direct numerical simulation) is used to predict onset of draw resonance. In this case the periodic solution is obtained even for high values of the Draw ratio (Fortin *et al.*, 1995).

If this represents an important increase in the computation complexity, it brings also important precision illustrated in the following by two examples obtained at a Draw ratio $Dr = 18$ using the tracking method and modelling both extrusion and stretching.

- Figure 15a presents the mesh and the flow domain computed for an aspect ratio $\varepsilon = 1/15$. A significant swelling at the die exit is observed as it would be expected that drawing will eliminate die swell. This explains that the experimental critical Draw ratios are always less than the theoretical ones (figure 2). The dominant eigenvalue ($\lambda = -0.084 + i11.99$) is very close to the limit of stability (real (λ) = 0). It is interesting to notice that this critical Draw ratio $Dr^* = 18$ accounting for the transition between the slit die and the stretching flow is near the critical Draw ratio of the 1D membrane model $Dr^* = 20.2$.
- Figure 15b presents the mesh and the flow domain computed for an aspect ratio $\varepsilon = 1/5$. There is no more visible swelling in this case and the flow is more stable as the real part of the eigenvalue ($\lambda = -0.38 + i12.149$) is much more negative. It points out that 2D simulation is required to determine stability conditions when the stretching distance decreases. Figure 16 illustrates the variation of the real part of the dominant eigenvalues as a function of the stretching distance.

4.4. Influence of the rheology

As a first approach, the viscoelastic behaviour of the polymer may be introduced through the simple upper-convected Maxwell (UCM) model which writes for the constant width model:

$$\sigma'_{xx} + \mu \left(\frac{\partial \sigma'_{xx}}{\partial t} + u \frac{\partial \sigma'_{xx}}{\partial x} - 2\sigma'_{xx} \frac{du}{dx} \right) = 2\eta \frac{du}{dx} \quad (8a)$$

$$\sigma'_{zz} + \mu \left(\frac{\partial \sigma'_{zz}}{\partial t} + u \frac{\partial \sigma'_{zz}}{\partial x} + 2\sigma'_{zz} \frac{du}{dx} \right) = -2\eta \frac{du}{dx} \quad (8b)$$

μ is the relaxation time and σ'_{xx} and σ'_{zz} are the extra-stress components of the stress tensor. The thin shell approximation writes:

$$\sigma_{xx} = \sigma'_{xx} - \sigma'_{zz} \quad (8c)$$

Solving stationary equations is not possible for every value of the Draw ratio Dr and the Deborah number De (it is the non-dimensional value of the relaxation time μ : $De = \mu \frac{u_0}{L}$).

This has been mentioned by Denn *et al.* (1975) and Antukar and Co (1988) who pointed out the existence of an unattainable drawing region in the vicinity of which the stretching force increases by several orders of magnitude (figure 17) and this is related to the dramatic increase of the elongation viscosity observed for the upper-convected Maxwell model. Even the use of more realistic viscoelastic models, limiting the increase of the elongation viscosity, leads to non-physical values of the stretching force (Silagy *et al.*, 1998). This could explain web breakage experimentally observed by Bourrigaud *et al.* (2006) for a collection of LDPE of varying viscoelasticity (figure 5). It is interesting to notice that the shape of the experimental film stretching limit is similar to the theoretical one, even if the experimental Draw ratios at rupture are more important than the ones theoretically predicted with the upper-convected Maxwell model.

For stability analysis, equations [1, 3, 8] are linearized in the same way as in the preceding paragraph. Figure 18 discriminates stable and unstable drawing conditions in the (Dr, De) plane for different values of the film shape factor A . At low Deborah number, which corresponds to a weak elasticity of the polymer, a low extrusion velocity or a long stretching distance, the critical draw ratio Dr^* is slightly dependent on the film shape factor A . Above a critical Deborah number De^* , which decreases markedly when the film shape factor increases, the periodic instability disappears. It is note-worthy to observe another stable region, for small Deborah numbers, at high draw ratios. This is not a mathematical artifact and an US patent has been applied (Chambon *et al.*, 1998) to draw films in these super-stable conditions. Silagy *et al.* (1998) and Kim *et al.* (2005) coupled the UCM model with a 2D membrane model accounting for width and thickness reduction. Kim *et al.* (2005) computed the transient thickness and width responses to small perturbations using a time-space numerical scheme. Shin *et al.* (2007a) developed the same approach but with a Phan-Thien Tanner model which limits the increase of the elongation viscosity.

These models lead to the following interesting conclusions about the stability of the cast film process.

- For short stretching distances, periodic thickness and width instabilities may be observed for a Draw ratio higher than a critical value around 20.

- Increasing the stretching distance will stabilize the process, due to both neck-in and cooling phenomena, but then the dog bone defect develops which necessitates trimming lateral sides of the film.
- Curiously, decreasing the stretching length to a distance of the order of magnitude of the die gap dimension will also stabilize the process.
- Using polymers of increasing viscoelasticity only slightly affects the web stability until a critical value above which the process becomes much more stable. The development of periodic instabilities is then no more a limitation, but web rupture may be observed. Let us point out that swelling at die exit will increase too and it is expected that it modifies the critical Draw ratio computed from the membrane model. Accounting for the coupled flow in the die and along the stretching distance for a viscoelastic fluid remains a challenge for a viscoelastic behavior as it is difficult in this case to deal with the stress singularity at die exit.

5. Fibre spinning

The basic equations of the fibre spinning process are essentially the same as for the constant width cast-film process. As a consequence the critical Draw ratio in isothermal Newtonian fibre spinning is equivalent ($Dr^*=20.2$) (Kase and Matsuo, 1965; Pearson and Matovich, 1969; Kase, 1974; Ishihara and Kase, 1975; Fischer and Denn, 1975; Demay and Agassant, 1982) and this is in agreement with experiments presented in paragraph 2.

In high velocity fibre spinning process (up to 5000 m/mn for Polyamide or Polyester) the stretching distance is important (several meters) and additional air-jet is applied in order to cool the filament which makes the process highly non-isothermal (Kase and Matsuo, 1965). The first linear stability analysis show (Shah and Pearson, 1972; Demay and Agassant, 1982) that the critical Draw ratio increases rapidly with the non-dimensional heat transfer coefficient when neglecting crystallization. This is in agreement with PET experiments (figure 19).

When introducing a viscoelastic UCM constitutive equation, the same phenomena are obtained as in the constant width cast-film situation (Fisher and Denn, 1976; Demay, 1983): an unstable region with the development of periodic instabilities at moderate Deborah numbers and intermediate Draw ratios, and an unattainable region at high Deborah number and high Draw ratios where the stretching force becomes infinite which would explain filament breakage. This is consistent with experiments (figure 2). More realistic viscoelastic models have been introduced by Lee *et al.* (2001) as Jung *et al.* (1999) coupled the UCM model and heat transfer. Lee *et al.* (2005), Shin *et al.* (2006) as well as Kohler and McHugh (2007, 2008) introduced stress induced crystallization and the corresponding crystallization energy in the temperature balance equation. Kohler and McHugh (2007, 2008) used a linear stability analysis and both Giesekus and Pom-Pom viscoelastic models to describe the response of the spinning line to a small variation of a spinning parameter in stable processing conditions. Interestingly, Shin *et al.* (2006) followed the real part of the dominant eigenvalue as a function of the take-up speed and pointed out the stabilizing effect of the necking phenomenon.

The following conclusions may be drawn for the fibre spinning process.

- As soon as the stretching distance and the cooling conditions are important, the periodic instability is not a true limitation.
- When increasing the extrusion velocity or (and) the relaxation time at constant Draw ratio, the stretching force increases dramatically which induces breakage.

- The rheology of the polymer during the crystallization step, especially at the high cooling rates encountered in the process, is not well mastered and this is the main limitation of the existing models (Jarecki and Ziabicki, 2004).

4.3. Film Blowing

At a first glance, one may consider that film blowing is simply a non-isothermal rolled up cast-film process, with a uniform thickness and with an increasing width instead of a width reduction (neck-in). Heat transfer would stabilize the process and viscoelasticity would cause web breakage at high Draw ratios. However experiments listed in section 2 showed unexpected phenomena: the existence of axisymmetric instabilities (which after unrolling correspond to both thickness and width variations) but also of non-axisymmetric instabilities. The reason is that the molten polymer tube is subjected to a Draw ratio, but also to a pressure differential (between the air inside the bubble and the atmospheric pressure) which induces a Blow-up ratio (*Bur*) and that is the combination of these two orthogonal drawings which makes the stability of the process much more complex.

It is surprising that modeling such a widely used process presents so many mathematical difficulties. All models use a membrane approximation leading to a system of partial differential equations according to the drawing distance z and time t . Computation of the steady state solution remains a numerical challenge for some operating conditions: both non existence or multiplicity of numerical solutions are found according to processing parameters values. The early steady state Newtonian isothermal model (Pearson and Petrie, 1970) has been extended to account for non-isothermal effects (Han and Park, 1975) coupled with crystallization (Kanai and White, 1984, 1985). Introducing an isothermal Maxwell (UCM) viscoelastic constitutive equation may lead to multiple solutions depending on the boundary conditions (Cain and Denn, 1988). Andre *et al.* (1998) studied the Maxwell non-isothermal film blowing process and pointed also out that no or multiple solutions may be obtained depending on the processing conditions. Hyun *et al.* (2004) introduced a viscoelastic Phan-Thien Tanner (PTT) non isothermal model. Doufas and McHugh (2001) and Pirkle and Braatz (2010) introduced flow induced crystallization with a two-phase model.

If the time dependent equations for the axisymmetric model were early introduced, the transient studies remain difficult because the boundary condition inside the bubble is not clear (fixed air volume or fixed pressure as a function of time). Yeow (1976), Cain and Denn (1988), Yoon and Park (1999) assume a Newtonian isothermal behavior and developed the same kind of linear stability analysis as in fibre spinning or cast film. They point out the big influence of the boundary condition inside the bubble on the instability onset. Pirkle and Braatz (2003) performed time dependent simulations and obtained the steady state result by integrating transient equations for a sufficient long time. Shin *et al.* (2007b) studied the stability of a PTT non-isothermal model as Henrichsen and McHugh (2007) used a viscoelastic Giesekus constitutive equation and compared there results to LDPE film blowing experiments. Both used a constant air volume condition inside the bubble.

All these models are only focused on the axisymmetric instabilities. Following Housiasdas and Tsamopoulos (1998), Laffargue *et al.* (2010) wrote and solved the film blowing equations in the frame affixed to the die geometry. This leads to complex developments which are detailed in Laffargue (2003) and Laffargue *et al.* (2010) but this allows capturing both axisymmetric and helical instabilities. Each variable (bubble radius,

bubble thickness, velocity, vertical stress, pressure, temperature...) is expressed as the sum of the stationary solution and a perturbation which writes:

$$X(t, z, \varphi) = \bar{X}(t, z) + \exp(\lambda t + im\varphi)\hat{X}(z) \quad (9)$$

In this equation X corresponds to any geometrical, kinematics, stress or temperature variable listed before. \bar{X} is the corresponding stationary solution and \hat{X} is an eigenfunction. The complex number λ is as previously an eigenvalue describing growth or decay of perturbations. The positive integer m is the azimuthal wave number: $m=0$ corresponds to an axisymmetric instability as $m=1$ corresponds to a helical instability (higher order instabilities ($m>1$) have not been investigated yet). Figure 20 shows the real part of the most important eigenvalue as a function of the Draw ratio for $m=0$ (axisymmetric case) and for $m=1$ (helical case) when the Blow-up ratio (Bur) is 2. For $m=0$, the eigenvalue becomes positive for a Draw ratio of 29, as the eigenvalue corresponding to $m=1$ is negative. This means that the axisymmetric instability will be activated. On the contrary, figure 21 shows the real part of the eigenvalue corresponding to $m=1$ as a function of Bur for a fixed $Dr=6$. The real part of the eigenvalue remains negative till $Bur=3.5$ and then becomes positive. In that blowing situation the eigenvalue corresponding to $m=0$ is negative which means that the helical instability will be activated. Figure 22 summarizes the results in the (Dr , Bur) plane: When varying the temperature gradient along the bubble (which means varying the air flow in the surrounding air ring) it is possible to build an envelope delimiting stable and unstable film blowing conditions (figure 23). This figure allows drawing interesting conclusions for the stability of the film blowing process:

- For given heat transfer conditions, increasing the Blow-up ratio stabilizes first the process (which means it is possible to impose more important Draw ratios and so to decrease significantly the film thickness in stable conditions) as it was likely to speculate the contrary.
- Above a critical Bur , Dr needs to decrease in order to remain in stable conditions.
- This “stability hill” is less pronounced when the temperature gradient (the air flow in the surrounding ring) increases.

Recently Lee *et al.* (2011a) showed that crystallization may stabilize the film blowing process as in fibre spinning. Using a constant blowing pressure inside the bubble in a viscoelastic non-isothermal model, Lee *et al.* (2011b) showed very different results than with the classical constant air volume boundary conditions.

5. Conclusions

Instabilities are encountered in most polymer forming processes. In extrusion or co-extrusion, these instabilities are directly linked to the viscoelastic behaviour of the polymer. In fibre and film stretching processes, drawing instabilities are present even for purely Newtonian fluids which means that their occurrence is, at the first order, governed by dissipation minimization mechanisms. However heat transfer and viscoelasticity will influence the onset and the development of the defect, and even suppress it. In shear dominant flows, as encountered in extrusion dies, sophisticated constitutive equations have to be used in order to account for instabilities. In fluid stretching operations, even a simple constitutive equation, as for example the upper-convected Maxwell model, is able to capture the main features. The reason is that in confined flows, a wide distribution of shear rates is present, as

in fluid stretching the elongation rates remain within a narrow range which induces activation of a dominant relaxation time.

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Captions for the figures

Figure 1: Recording of diameter vs time showing the response to an increase of take-up speed. The stretching ratio goes from 46.6 to 57 for (a), from 57 to 65.6 for (b) and from 65.6 to 75.3 for (c) (from Demay and Agassant, 1985).

Figure 2: Theoretical and experimental critical draw-ratio Dr^* vs. Deborah number De . A, B, C, D, refer to different polyesters. (\blacktriangle) corresponds to $u_0=2.09$ cm/s. (\bullet) corresponds to $u_0=4.18$ cm/s (from Demay and Agassant, 1985).

Figure 3: Experimental measurement of thickness (a) and width (b) instabilities in the polyester cast-film process; $Dr = 28.4$ (from Barq *et al.*, 1990).

Figure 4: Stretching force as a function of time for various take-up velocities (from Agassant *et al.*, 2006).

Figure 5: Experimental unattainable zone for different LDPE films produced by the cast film process (from Bourrigaud *et al.*, 2006).

Figure 6: Axisymmetric film blowing instability.

Figure 7: Helical film blowing instability.

Figure 8: Bubble radius variation and location of the centre of the bubble as a function of time for varying Draw ratio and a constant Blow up ratio ($Bur= 2.75$) (from Laffargue *et al.*, 2002).

Figure 9: Bubble radius variation and location of the centre of the bubble as a function of time for varying Draw ratio and a constant Blow up ratio ($Bur=3.25$) (from Laffargue *et al.*, 2002).

Figure 10: Experimental stability map with the same LLDPE and various film blowing machines (from Laffargue *et al.*, 2010)

Figure 11: Sketch of a constant width cast-film model.

Figure 12: Influence of the shape factor A on the critical Draw ratio Dr^* : (—) 1D model; (\circ) 2D stable situation; (\bullet) 2D unstable situation (from Silagy *et al.*, 1998).

Figure 13: 2D cast-film model, film thickness as a function of time after imposing a small initial perturbation. The film shape factor is $A = 0.6$. (a) $Dr = 10$; (b) $Dr = 15$; (c) $Dr = 18$; (d) $Dr = 21$; (e) $Dr = 24$; (f) $Dr = 27$; (g) $Dr = 31.5$; (h) $Dr = 36$ (from Silagy *et al.*, 1998)

Figure 14: 2D Newtonian unsteady cast-film computation : $Dr = 33$; $A = 0.44$; (a) width fluctuations ; (b) film thickness fluctuations at the periphery of the film; (c) Film thickness fluctuations in the centre of the film (from Silagy *et al.*, 1998).

Figure 15: Coupled die and stretching flow computation: (a) $e_0/L=1/15$; (b) $e_0/L=1/5$.

Figure 16: Real part of the leading eigenvalue as a function of the stretching distance (a dimensionless value is obtained using the residence time L/u_0).

Figure 17: Unattainable stretching zone as a function of the Draw ratio and the Deborah number.

Figure 18: 1D viscoelastic cast-film model: influence of the film shape factor A on the drawing stability (from Silagy *et al.*, 1998).

Figure 19: Critical Draw ratio as a function of the Stanton number; (—) theoretical result (from Demay and Agassant, 1982); (●) measurements (from Demay and Agassant, 1985).

Figure 20: Real part of the dominant eigenvalue as a function of the Draw ratio for the axisymmetric mode ($m = 0$) and the helical mode ($m = 1$) ($Bur = 2$) (from Laffargue *et al.*, 2010).

Figure 21: Real part of the dominant eigenvalue as a function of the Blow-up ratio for the helical mode ($m = 1$) ($Dr = 6$) (from Laffargue *et al.*, 2010).

Figure 22: Stability curve in the (Dr, Bur) frame (from Laffargue *et al.*, 2010).

Figure 23: 3D stability map as a function of the Draw ratio, the Blow-up ratio and the temperature gradient (from Laffargue, 2003).

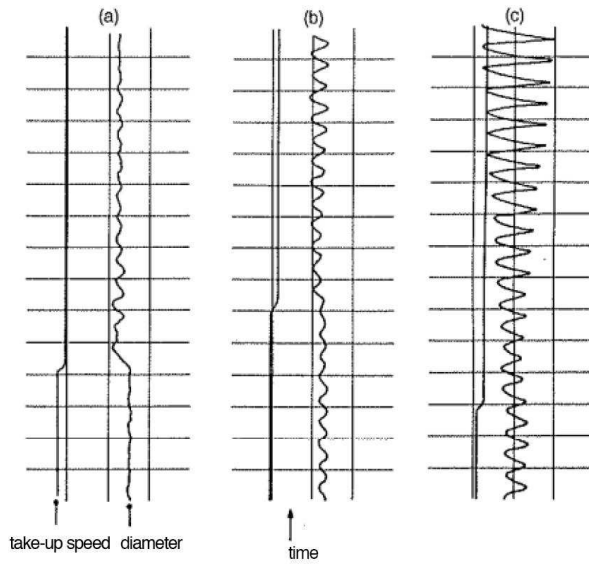


Figure 1

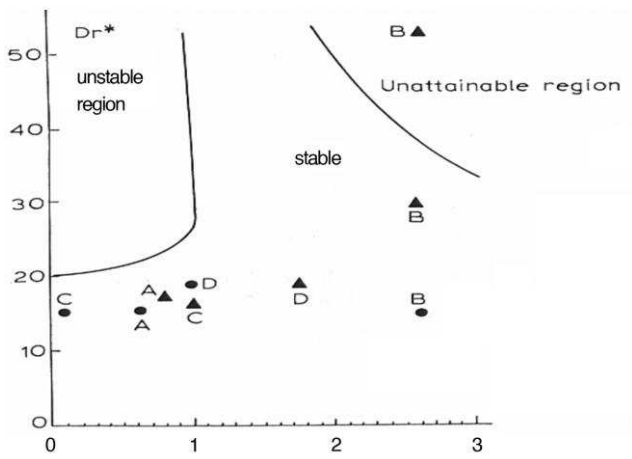


Figure 2

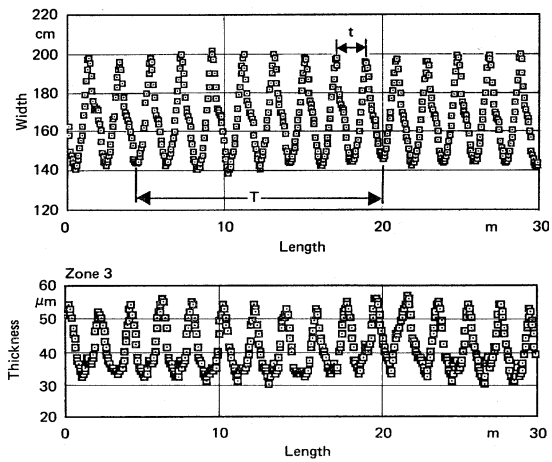


Figure 3

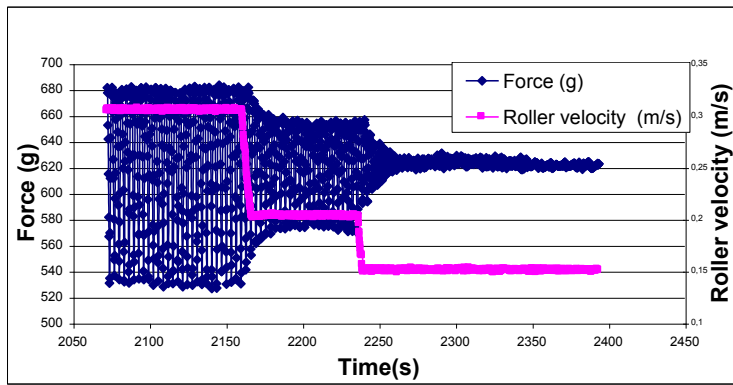


Figure 4

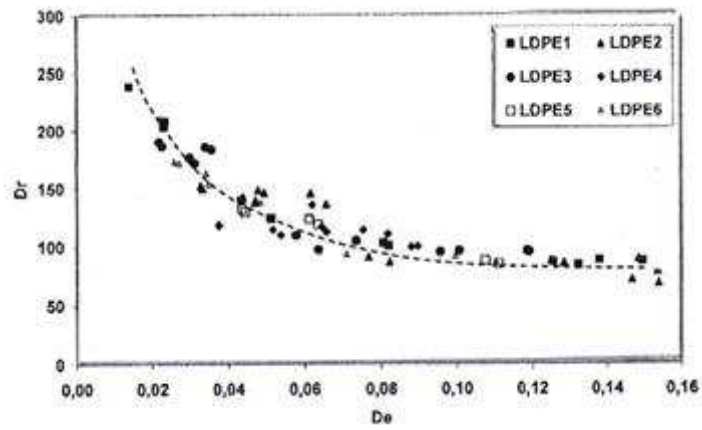


Figure 5

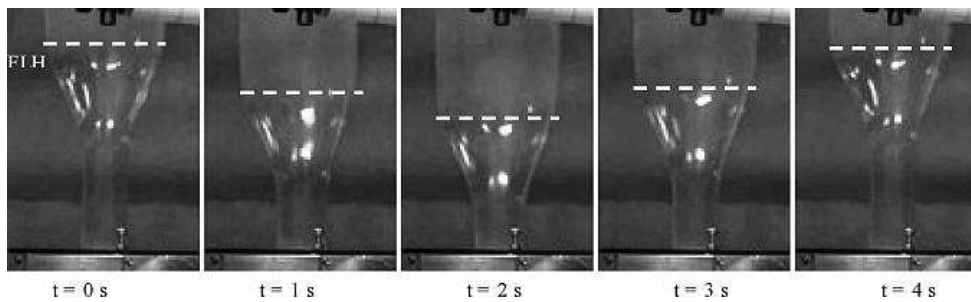


Figure 6

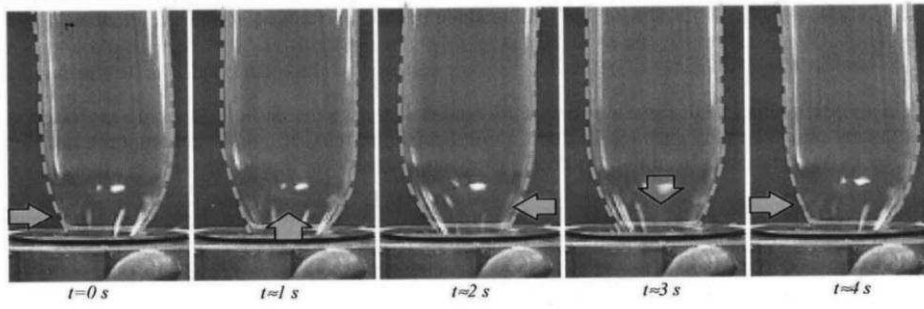


Figure 7

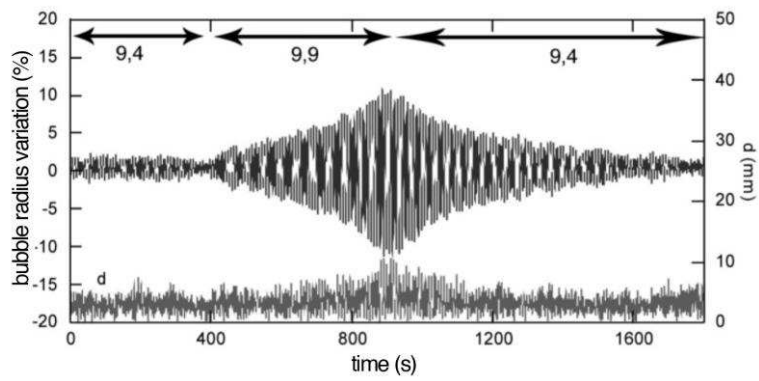


Figure 8

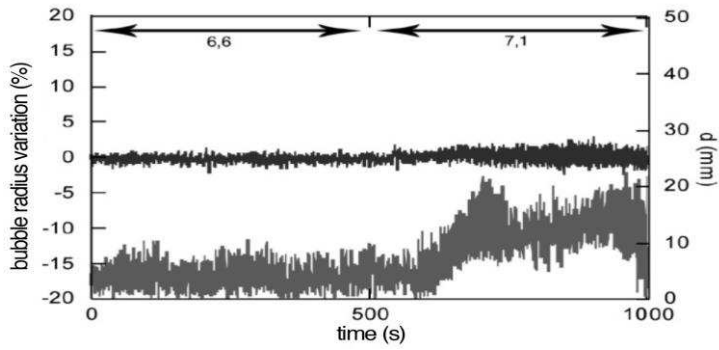


Figure 9

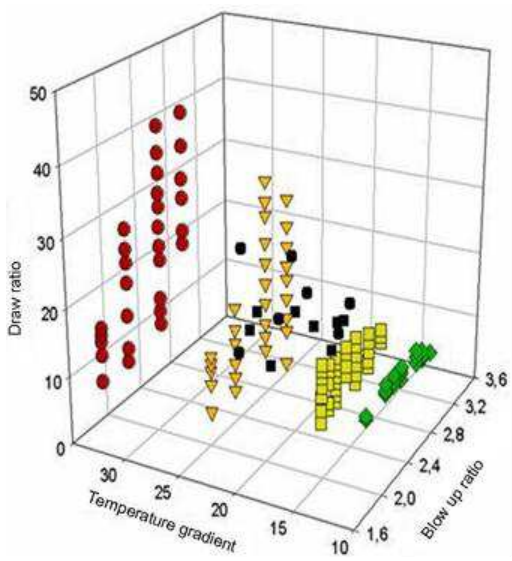


Figure 10

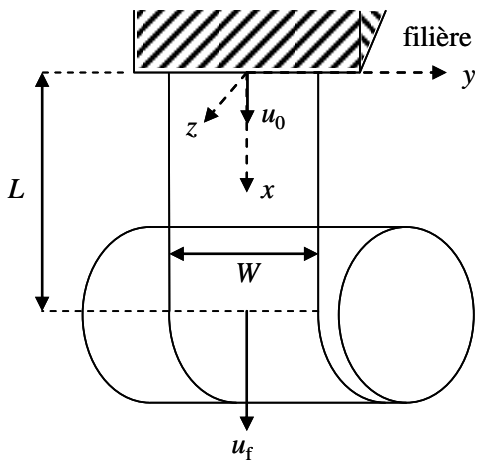


Figure 11

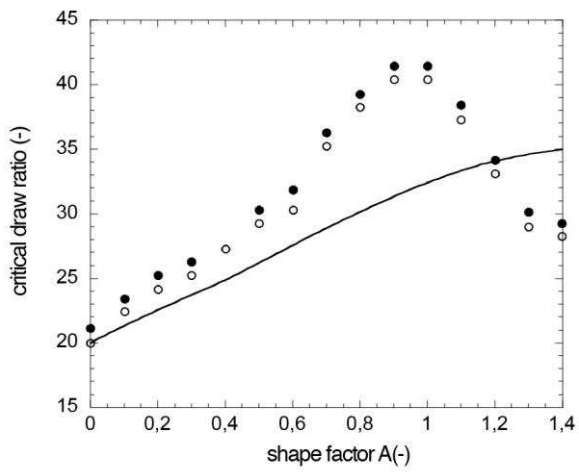


Figure 12

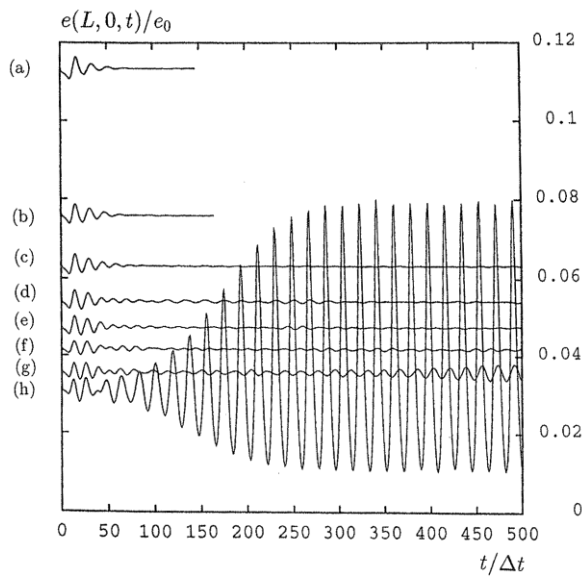


Figure 13

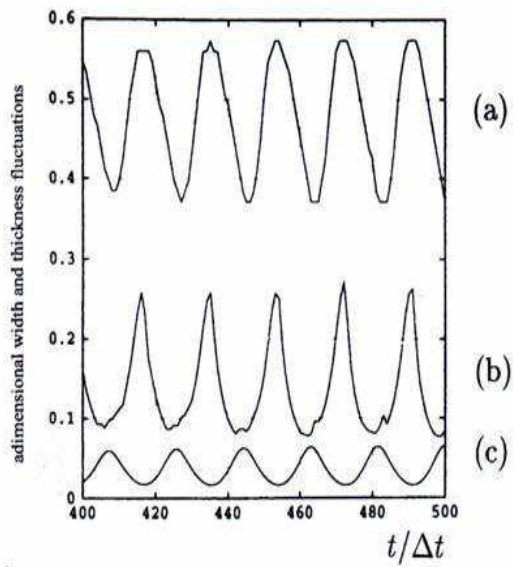


Figure 14

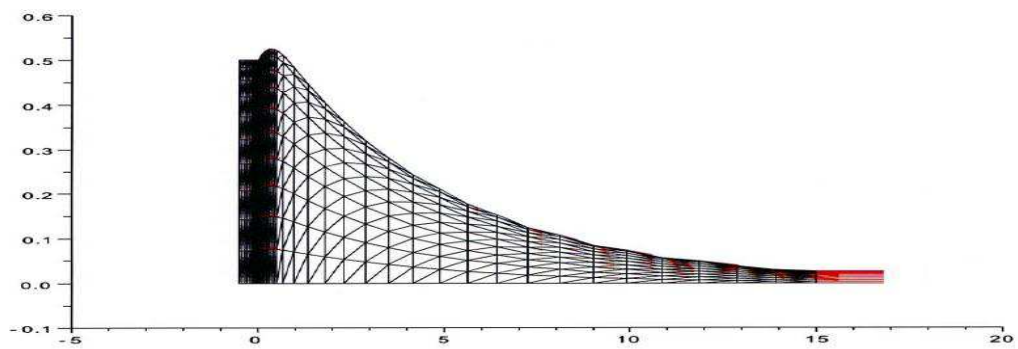


Figure 15a

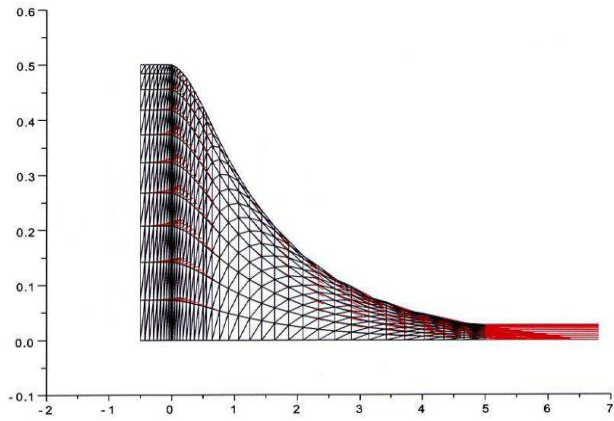


Figure 15b

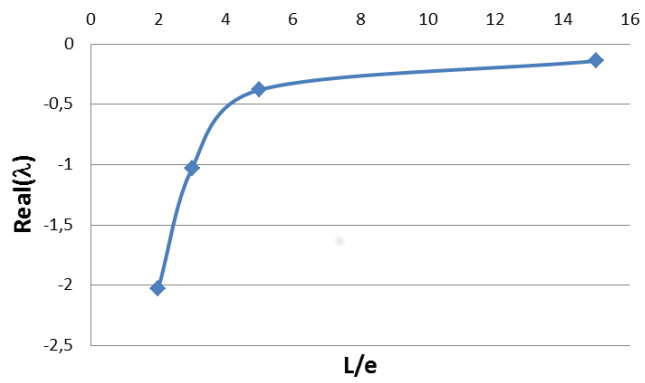


Figure 16

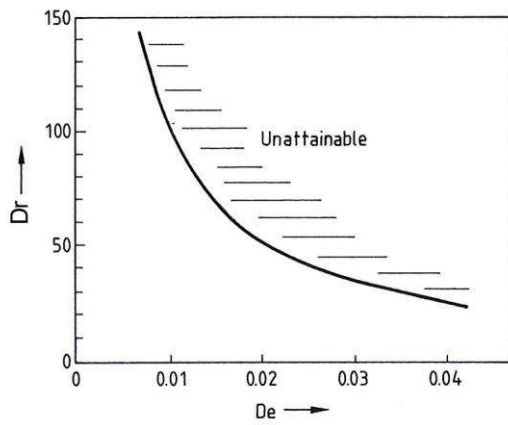


Figure 17

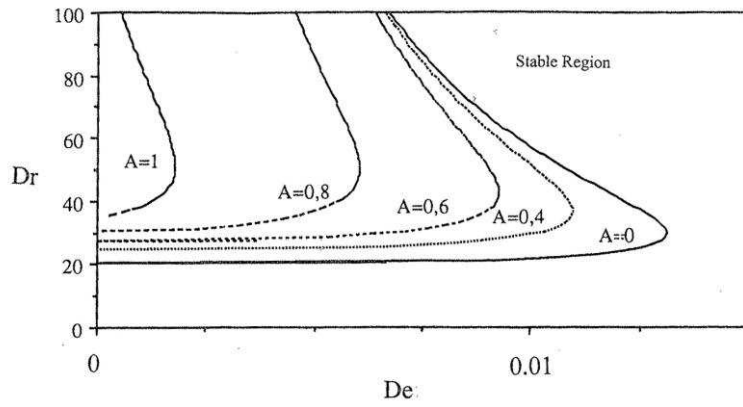


Figure 18

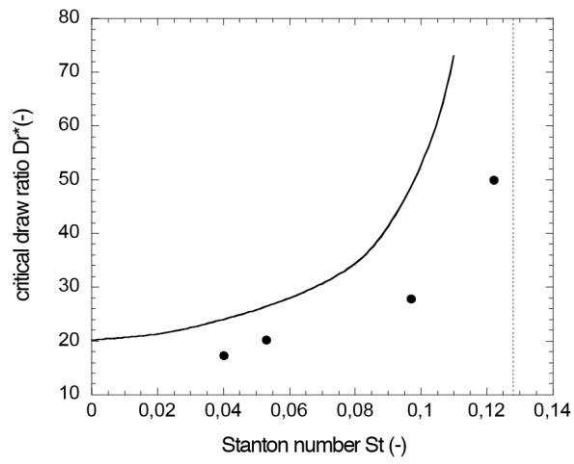


Figure 19

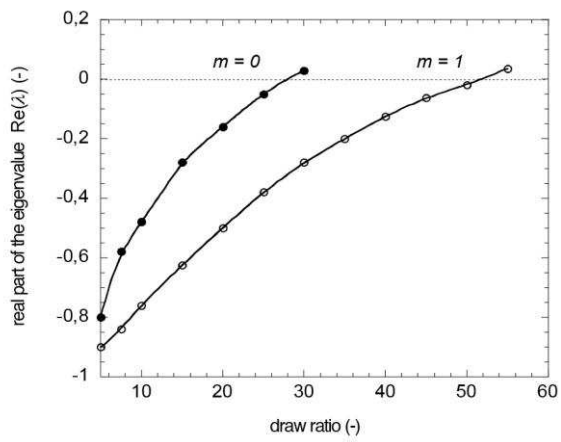


Figure 20

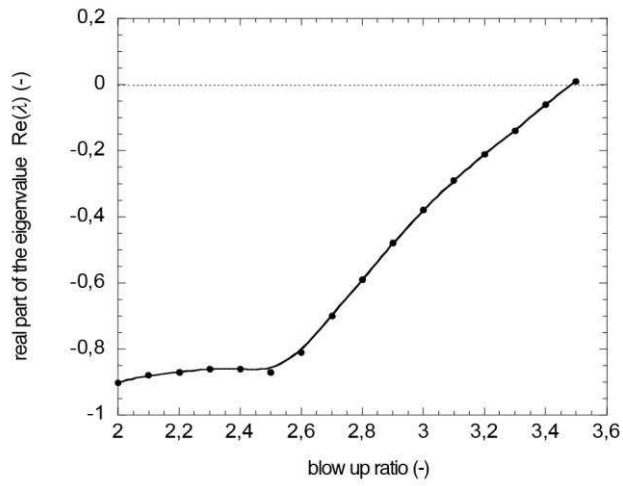


Figure 21

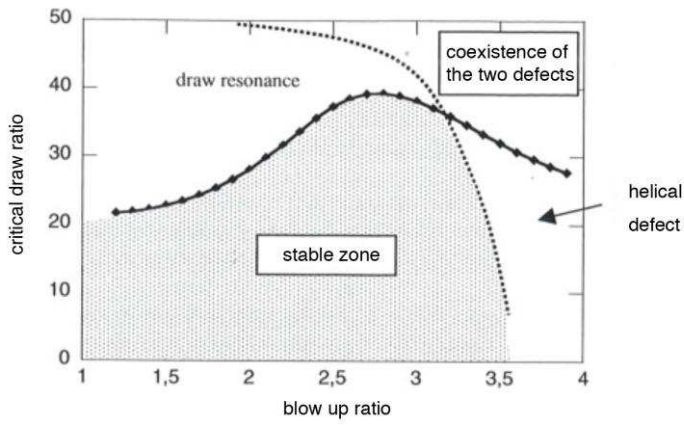


Figure 22

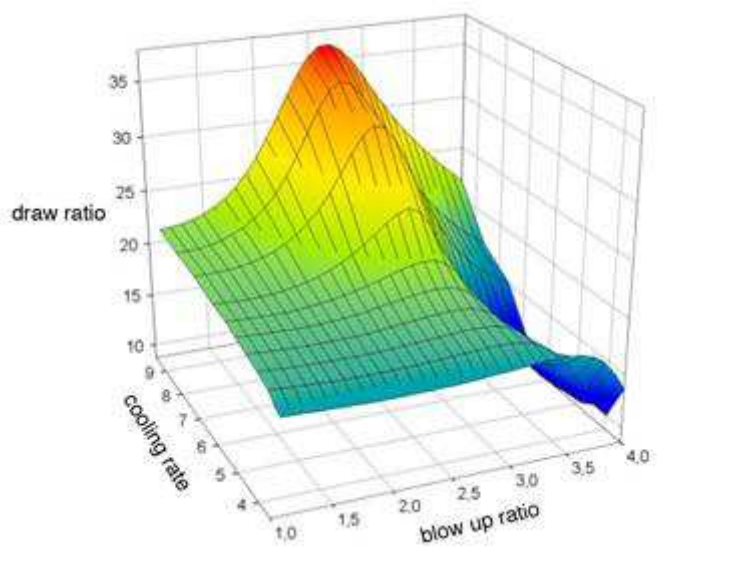


Figure 23